

# A Kind of Cubic $C^1$ —Interpolations in the $n$ -dimensional Finite Element Method\*

Ren Hong Wang and Xi Quan Shi

(Jilin University)

## § 1 Introduction

As is well known that the multivariate spline function plays an important role in both theory and application. The paper [1]—[11] have studied the multivariate spline functions and obtained a lot of results concerning this topic. Especially in [3], the existence theorem has been shown for the case of  $n$ -dimensional spline functions. A. Zenisek [10] and P. Alfeld [11] have established some of results about the tetrahedron partition. In this paper, we will show a kind of cubic  $C^1$ —interpolations for any  $n$ -simplicial partition in  $\mathbf{R}^n$ . Of course, some of the subdivisions will be needed.

## § 2 The structure of cubic $C^1$ —interpolation

Let  $\Omega_n$  be a polyhedron in  $\mathbf{R}^n$ ,  $\Delta_n$  a simplicial subdivision of  $\Omega_n$ , and  $i$ -simplex  $S_j^{(i)}$ ,  $i = 0, 1, \dots, n$ ;  $j = 1, 2, \dots, T_i$ . Suppose  $\overline{\Delta}_n$  is a refining subdivision of  $\Delta_n$  formed by the following steps:

- i). Take an interior point  $O_j^{(i)}$  in each  $i$ -simplex  $S_j^{(i)}$ , respectively,  $i = 2, 3, \dots, n$ ;  $j = 1, 2, \dots, T_i$ .
- ii). Let  $S_{j,0}^{(0)}, S_{j,1}^{(0)}, \dots, S_{j,i}^{(0)}$  be the vertices of the  $i$ -simplex  $S_j^{(i)}$ , we join  $O_j^{(i)}$  to each  $S_{j,k}^{(0)}$  respectively,  $i = 2, \dots, n$ ;  $j = 1, 2, \dots, T_i$ ;  $k = 0, 1, \dots, i$ .
- iii). Let  $S_j^{(i)}, S_{j,k}^{(0)}$  ( $0 \leq k \leq i$ ) be the same as ii).  $S_{j,i_0}^{(0)}, S_{j,i_1}^{(0)}, S_{j,i_2}^{(0)}, \dots, S_{j,i_m}^{(0)}$  the vertices of the  $(m)$ -simplex  $S_{j,A}^{(m)}$  and  $O_{j,A}^{(m)}$  be the interior point of  $S_{j,A}^{(m)}$ . We join  $O_j^{(i)}$  to each  $O_{j,A}^{(m)}$ , respectively, where  $i = 3, \dots, n$ ;  $j = 1, 2, \dots, T_i$ ;  $m = 2, 3, \dots, i-1$ ; and  $A = \{i_0, i_1, \dots, i_m\} \subset \{i = 1, 2, \dots, m\}$ .
- iv). When two  $n$ -simplices  $S_i^{(n)}$  and  $S_j^{(n)}$  have a  $(n-1)$ -dimensional common surface  $S_k^{(n-1)}$ , the interior points  $O_i^{(n)}, O_j^{(n)}, O_k^{(n-1)}$  have to be collinear.

It is obvious that the refining subdivision  $\overline{\Delta}_n$  exists, in fact, we can take

\* Received August 10, 1987.

This paper was presented at the fifth conference on Approximation Theory of China held at Zheng Zhou April 1987.

point  $O_i^{(n)}$  as the center of inscribed sphere of  $S_i^{(n)}$ , where  $i = 1, 2, \dots, T_n$ . When two  $n$  simplices  $S_i^{(n)}$  and  $S_j^{(n)}$  have a common surface  $S_k^{(n-1)}$ , we set point  $O_k^{(n-1)}$  as the intersection point of the surface  $S_k^{(n-1)}$  and the straight line  $\overline{O_i^{(n)}O_j^{(n)}}$ , the others point  $O_j^{(i)}$  may be any interior point of  $S_j^{(i)}$ , respectively.

For the refining subdivision  $\overline{\Delta}_n$ , we have the interpolation conditions as follows :

- 1). Values of position, gradient at  $S_i^{(0)}$ ,  $i = 1, 2, \dots, T_0$ .
- 2). Let  $\bar{S}_i^{(1)}$  be the mid-point of  $S_i^{(1)}$ ,  $e_{i_0}$  a unit direction vector of  $S_i^{(1)}$ , and  $e_{i_j}$  the vectors satisfying the following conditions :

$$(e_{i_j}, e_{i_k}) = \delta_{j,k}.$$

where  $\delta_{j,k}$  is kronecker symbol,  $j, k = 0, 1, \dots, n-1$ . We give the directional derivatives  $\frac{\partial f}{\partial e_{i_j}}(\bar{S}_i^{(1)})$ ,  $j = 1, 2, \dots, n-1$ ;  $i = 1, 2, \dots, T_1$ .

For any simplicial subdivision  $\Delta_n$  of a polyhedron domain in  $\mathbf{R}^n$ , we define  $S_k^\mu(\Delta_n, \mathbf{R}^n) := \{S \in C^\mu(\Delta_n); \text{the restriction of } S \text{ to each } n \text{ simplex of } \Delta_n \text{ is a polynomial of degree } k\}$

We have

**Theorem 1.** The interpolation conditions 1) and 2) determine a unique multivariate spline function  $S \in S_1^1(\overline{\Delta}_n, \mathbf{R}^n)$ , and

$$\dim S_1^1(\overline{\Delta}_n, \mathbf{R}^n) = (n+1)T_0 + (n-1)T_1.$$

To prove Theorem 1., we need the following three Lemmas.

**Lemmas 1.** Denote by  $V[X_1, X_2, \dots, X_{n+1}]$  the  $n$ -simplex with vertices  $X_1, X_2, \dots, X_{n+1}$ . If  $X_0 \in V[X_1, \dots, X_{n+1}]$ , then

$$\sum_{i=1}^{n+1} u_i (X_i - X_0) = 0,$$

where  $(u_1, u_2, \dots, u_{n+1})$  is the barycentric coordinates of  $X_0$ .

Denote by  $D_{i,j} = D_{(X_j - X_i)}$  the (unnormalized) directional derivative of  $(X_j - X_i)$ , we have

**Lemma 2.** Let  $X_1, X_2, X_3$  be the vertices of a triangle  $\Delta_{123}$ , and  $P(x)$  a polynomial of degree 3 satisfying the following conditions :

$$P(X_i) = f(X_i),$$

$$D_{i,j}P(X_i) = D_{i,j}f(X_i), \quad i, j = 1, 2, 3.$$

Then

$$P(x) = du_1u_2u_3 + \sum_{i=1}^3 \left( \sum_{j=1}^3 u_j D_{i,j}f(X_i) + (3-2u_i)f(X_i) \right) u_i^2$$

and

$$D_{i,k}P\left(\frac{X_i + X_j}{2}\right) = \frac{1}{4}d + \frac{1}{4}(D_{i,k}f(X_i) + D_{i,k}f(X_j)) - \frac{1}{2}(D_{i,j}f(X_i) + 3f(X_i)),$$

where  $i, j, k = 1, 2, 3$ ;  $i \neq j \neq k \neq i$ ;  $d$  is a real constant and the vector  $(u_1, u_2, u_3)$

is the barycentric coordinates of  $X$ .

Similarly, we have

**Lemma 3.** Let  $X_1, X_2, X_3, X_4$  be the vertices of a tetrahedron  $V[X_1, X_2, X_3, X_4]$ , and  $P(x)$  a polynomial of degree 3 satisfying the following conditions:

$$P(X_i) = f(X_i); D_{i,j}P(X_i) = D_{i,j}f(X_i), \quad i, j = 1, 2, 3, 4.$$

Then

$$P(x) = \sum_{i=1}^4 [d_i u_i^{-1} \prod_{j=1}^4 u_j + (\sum_{j=1}^4 u_j D_{i,j} f(X_i) + (3 - 2u_i) f(X_i)) u_i^2],$$

and

$$D_{i,k}P\left(\frac{X_i + X_j}{2}\right) = \frac{1}{4}d_i + \frac{1}{4}(D_{i,k}f(X_i) + D_{i,k}f(X_j)) - \frac{1}{2}(D_{i,j}f(X_i) + 3f(X_i)),$$

where  $(i, j, k, l)$  takes all of the permutations of the four numbers 1, 2, 3, 4;  $d_1, d_2, d_3, d_4$  are real constants, and the vector  $(u_1, u_2, u_3, u_4)$  is the barycentric coordinates of  $X$ .

The proof of Theorem 1.

Without loss of generality, we will only prove the theorem in the space  $\mathbf{R}^3$ .

First, Let subdivision  $\triangle_3$  have only one tetrahedron  $V[X_1, X_2, X_3, X_4]$ , and the refining subdivision  $\overline{\triangle}_3$  be shown in Fig. 1, we aim at a function  $S \in S_3^1(\overline{\triangle}_3, \mathbf{R}^3)$  satisfying the conditions 1) and 2).

First of all, we consider the tetrahedron  $V_2 = V[O, X_1, X_2, X_4]$  (See Fig 2.). It is not difficult to verify that

$$\dim S_3^1(\overline{V}_2, \mathbf{R}^3) = 22,$$

where  $\overline{V}_2$  is the refining subdivision of  $V_2$  which is generated by  $\overline{\triangle}_3$ .

By using the condition 1) and 2) and the values of position, gradient at point  $O$ , we can obtain a unique function  $\overline{S}_2 \in S_3^1(\overline{V}_2, \mathbf{R}^3)$ .

Similarly, we can get the functions  $\overline{S}_i \in S_3^1(\overline{V}_i, \mathbf{R}^3)$ , where  $V_i$  and  $\overline{V}_i$  ( $i = 1, 2, 3, 4$ ) are similar to  $V_2$  and  $\overline{V}_2$  as above state.

Define the spline function  $S$  satisfying  $S|_{V_i} = \overline{S}_i$ , for each  $i$ , it is obvious that  $S \in S_3^0(\overline{\triangle}_3, \mathbf{R}^3)$ . Next we will get the values of position, gradient of  $S$  at the point  $O$ , such that  $S \in S_3^1(\overline{\triangle}_3, \mathbf{R}^3)$ .

In fact, in the process has been indicated as above, we used the directional derivatives  $D_{0,i}S(O)$  ( $1 \leq i \leq 4$ ) other than the gradients, where we have supposed  $O$  is origin.

In order to get the values of  $S(O)$  and  $D_{0,i}S(O)$ , we set

$$\sum_{i=1}^4 u_{0,i} D_{0,i}S(O) = 0, \quad \sum_{i=1}^4 u_{0,i} D_{0,i}S\left(\frac{X_j}{2}\right) \Big|_{\triangle_{OX_j}} = 0, \quad j = 1, 2, 3, 4. \quad (1)$$

where  $\triangle_{OX_j}$  represents the segment  $\overline{OX_j}$ ,  $D_{0,i} = D_{X_i}$ , and the vector  $(u_{0,1}, u_{0,2}, u_{0,3}, u_{0,4})$  is the barycentric coordinates of  $O$ .

Without loss of generality, suppose the corresponding values at points  $(X_i +$

$X_j)/2$  ( $i, j = 1, 2, 3$ ) appeared in the conditions 1) and 2) vanish.

According to (1) and Lemma 2, we have

$$\sum_{i=1}^4 u_{0,i} D_{0,i} S(O) = 0,$$

$$3S(O) + D_{0,i} S(O) = 2u_{0,4}(D_{i,0} f(\overline{i4}) + \frac{1}{4} D_{0,i} f(X_4)),$$

$$3S(O) + D_{0,4} S(O) = 2 \sum_{i=1}^3 u_{0,i} (D_{i,0} f(\overline{i4}) + \frac{1}{2} D_{0,i} f(X_4)) + u_{0,4} (3f(X_4) - \frac{1}{2} D_{0,4} f(X_4)).$$

Hence

$$\begin{aligned} S(O) &= u_{0,4}^2 f(X_4) - \frac{2}{3} u_{0,4}^2 D_{0,4} f(X_4) + \frac{4}{3} u_{0,4} \sum_{i=1}^3 u_{0,i} D_{i,0} f(\overline{i4}), \\ D_{0,i} S(O) &= 2u_{0,4} (D_{i,0} f(\overline{i4}) + \frac{1}{4} D_{0,i} f(X_4)) - 3S(O), \\ D_{0,4} S(O) &= 2 \sum_{i=1}^3 u_{0,i} (D_{i,0} f(\overline{i4}) + \frac{1}{2} D_{0,i} f(X_4)) \\ &\quad + u_{0,4} (3f(X_4) - \frac{1}{2} D_{0,4} f(X_4)) - 3S(O), \end{aligned} \quad (2)$$

where

$$f(\overline{i4}) = f\left(\frac{X_i + X_4}{2}\right); \quad i = 1, 2, 3.$$

To prove  $S \in S_3^1(\overline{\Delta}_3; \mathbf{R}^3)$ , we only need to prove the function  $S$  belongs to  $C^1$  on the joint of arbitrary two tetrahedrons in  $V_i$  ( $1 \leq i \leq 4$ ). Using conditions 1) and 2), for example, we have

$$D_{0,4} \overline{S}_3\left(\frac{X_i + X_j}{2}\right) = D_{0,4} \overline{S}_4\left(\frac{X_i + X_j}{2}\right), \quad i, j = 1, 2.$$

Moreover, from (1) and Lemma 1., we have

$$D_{0,4} \overline{S}_4(O) = D_{0,4} \overline{S}_3(O)$$

and

$$D_{0,4} \overline{S}_3\left(\frac{X_i}{2}\right) = D_{0,4} \overline{S}_4\left(\frac{X_i}{2}\right), \quad i = 1, 2.$$

Thus

$$D_{0,4} \overline{S}_3|_{\Delta O X_1 X_2} = D_{0,4} \overline{S}_4|_{\Delta O X_1 X_2}.$$

$$|_{V_3 \cup V_4} \in S_3^1(\overline{V}_3 \cup \overline{V}_4, \mathbf{R}^3). \text{ That being so } S \in S_3^1(\overline{\Delta}_3, \mathbf{R}^3).$$

According to Lemma 3, it is easy to get

$$S(x)|_{V_4} = (u_{4,1} D_{0,1} S(O) + u_{4,2} D_{0,2} S(O) + u_{4,3} D_{0,3} S(O) + (3 - 2u_{4,0}) S(O)) u_{4,0}^2,$$

where vector  $(u_{4,1}, u_{4,2}, u_{4,3}, u_{4,0})$  is the barycentric coordinates of  $X \in V_4$ .

Let the barycentric coordinates of  $O_2$  in the tetrahedron  $V[X_1, X_2, X_3, X_4]$  be the vector  $(u_{O_2,1}, u_{O_2,2}, u_{O_2,3}, u_{O_2,4})$ . Similarly we can obtain

$$\begin{aligned} S(O_2) &= u_{O_2,4}^2 f(X_4) - \frac{1}{3} u_{O_2,4} D_{O_2,4} f(X_4) + \frac{4}{3} u_{O_2,4} \sum_{i=1}^3 u_{O_2,i} D_{i,O_2} f(\overline{i4}), \\ D_{O_2,i} S(O_2) &= 2u_{O_2,4} (D_{i,O_2} f(\overline{i4}) + \frac{1}{4} D_{O_2,i} f(X_4)) - 3S(O_2), \end{aligned} \quad (3)$$

$$D_{O_2,4} S(O_2) = 2 \sum_{i=1}^3 u_{O_2,i} f(\overline{i4}) + \frac{1}{2} D_{O_2,i} f(X_4) + u_{O_2,4} (3f(X_4) - \frac{1}{2} D_{O_2,4} f(X_4)) - 3S(O_2)$$

where  $f(\overline{i4})$  are similar to (2);  $u_{O_2,2}=0$ ;  $D_{O_2,i} = D_{(X_i-O_2)}$  and  $i=1,3$ .

Suppose

$$f_1 = S[V(O, O_2, X_3, X_4)],$$

$$f_3 = S[V(O, O_2, X_1, X_4)],$$

$$f_4 = S[V(O, O_2, X_1, X_3)].$$

then  $(f_i - f_j)$  divides by  $\Pi_k^2$ , where  $(i, j, k)$  takes the all of the permutations of the three number 1, 3, 4, and  $\Pi_k$  is the plane determined by three points  $O, O_2$  and  $X_k$  ( $k=1, 3, 4$ ). We have

$$D_{O_2,0} f_1 = D_{O_2,0} f_3 = D_{O_2,0} f_4 \quad (4)$$

It means that the restriction of  $D_{O_2,0} S$  to the tetrahedron  $V_2$  is only a polynomial of degree 2, and

$$D_{O_2,0} S(X) \big|_{\Delta_{X_1 X_3 X_4}} = \sum_{i=1}^4 D_{O_2,0} f(X_i) u_{2,i} (2u_{2,i} - 1) + 4(u_{2,1} u_{2,3} D_{O_2,0} f(\overline{13}) + u_{2,3} u_{2,4} D_{O_2,0} f(\overline{34}) + u_{2,1} u_{2,4} D_{O_2,0} f(\overline{14}))$$

where the vector  $(u_{2,1}, u_{2,2}, u_{2,3}, u_{2,4})$  is the barycentric coordinates of  $X \in V_2$ , and  $u_{2,2} = 0$ . Denote by  $F(u_{2,1}, u_{2,3}, u_{2,4})$  the function defined by the above equality we have

$$\begin{aligned} D_{O_2,0} S(O_2) &= F(u_{O_2,1}, u_{O_2,3}, u_{O_2,4}), \\ D_{O_2,0} S\left(\frac{X_1 + O_2}{2}\right) &= F\left(\frac{1}{2} + \frac{1}{2} u_{O_2,1}, \frac{1}{2} u_{O_2,3}, \frac{1}{2} u_{O_2,4}\right), \\ D_{O_2,0} S\left(\frac{X_3 + O_2}{2}\right) &= F\left(\frac{1}{2} u_{O_2,1}, \frac{1}{2} + \frac{1}{2} u_{O_2,3}, \frac{1}{2} u_{O_2,4}\right), \\ D_{O_2,0} S\left(\frac{X_4 + O_2}{2}\right) &= F\left(\frac{1}{2} u_{O_2,1}, \frac{1}{2} u_{O_2,3}, \frac{1}{2} + \frac{1}{2} u_{O_2,4}\right). \end{aligned} \quad (5)$$

By using Lemma 3, the systems of equations (2), (3), (5), the condition 1) and 2), we can get the explicit expression of  $S$ . For example, the expression of  $S$  on the tetrahedron  $V(O, O_2, X_1, X_3)$  is

$$S(x) \big|_{V(O, O_2, X_1, X_3)} = \sum_{i=0}^3 [\overline{d_i} \overline{u_i} + \prod_{j=0}^3 \overline{u_j} + (\sum_{j=0}^3 \overline{u_j} D_{i,j} f(A_j) + (3 - 2\overline{u_i}) f(A_i)) \overline{u_i}^2]$$

where  $A_0 = O$ ,  $A_1 = X_1$ ,  $A_2 = O_2$ ,  $A_3 = X_3$ ;  $D_{i,j} = D_{(A_j - A_i)}$ ; the vector  $(\overline{u_0}, \overline{u_1}, \overline{u_2}, \overline{u_3})$  is the barycentric coordinates of  $x \in V(A_0, A_1, A_2, A_3)$ ;  $\overline{d_i} = 4D_{2,0} S(\frac{A_i + A_2}{2}) - (D_{2,0} S(A_i) + D_{2,0} f(A_i)) + 2(D_{2,i} S(A_2) + 3S(A_2))$ ,  $i=1, 3$ ; and  $\overline{d_i} = 4D_{3,i} f(\frac{A_1 + A_3}{2})$ ,  $i=0, 2$ .

For general subdivision  $\Delta_3$ , using the preceding results, we have established an interpolating function  $S$  such that  $S|_{S_i^{(3)} \in S_3^1(\overline{S}_i^{(3)}, \mathbf{R}^3)}$ ,  $i=1, 2, \dots, T_3$ ; and  $S \in S_3^0(\overline{\Delta}_3, \mathbf{R}^3)$ . In the next place, we will prove when tetrahedrons  $S_i^{(3)}$  and  $S_j^{(3)}$  have

a common surface  $S_k^{(2)}$ , the function  $S \in C^1(S_i^{(3)} \cup S_j^{(3)})$ . Let  $O_i^{(3)}, O_j^{(3)}, O_k^{(2)}$  be collinear, using (4), the restriction both of  $D_{\bar{k},i} S_i$  and  $D_{\bar{k},j} S_j$  to  $S_k^{(2)}$  are polynomials of degree 2. It follows from conditions 1) and 2) that

$$\frac{1}{L_{\bar{k},i}} D_{\bar{k},i} S_i|_{S_k} = -\frac{1}{L_{\bar{k},j}} D_{\bar{k},j} S_j|_{S_k^{(2)}},$$

where  $S_i = S|_{S_i^{(3)}}$ ;  $S_j = S|_{S_j^{(3)}}$ ;  $D_{\bar{k},i} = D_{(O_i^{(3)} - O_k^{(2)})}$ , and  $L_{\bar{k},i} = \|O_i^{(3)} - O_k^{(2)}\|$ .

Therefore  $S \in C^1(S_i^{(3)} \cup S_j^{(3)})$ , furthermore  $S \in S_3^1(\bar{\Delta}_3, \mathbb{R}^3)$ .

It is obvious that the interpolation scheme will reproduce the functions belonging to  $S_3^1(\bar{\Delta}_3, \mathbb{R}^3)$ , especially, it will reproduce the polynomials  $\in \mathcal{P}_3$ .

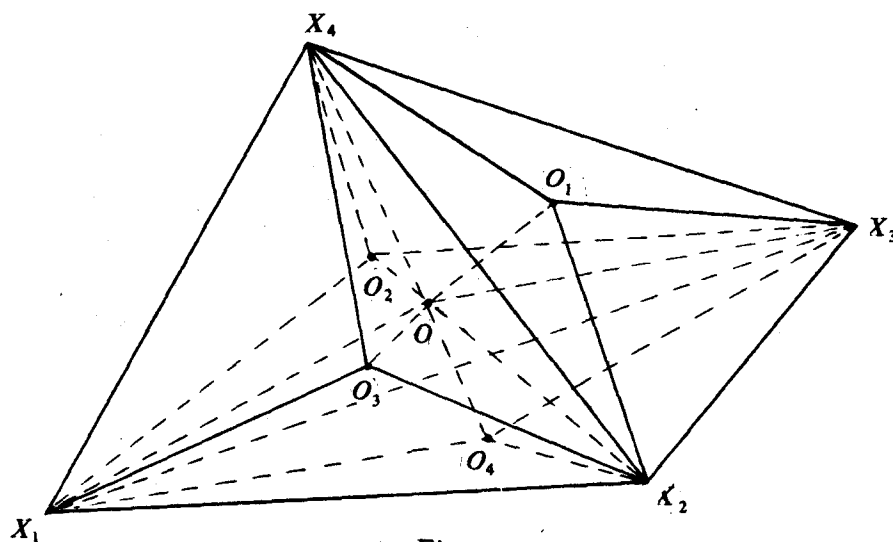


Fig. 1

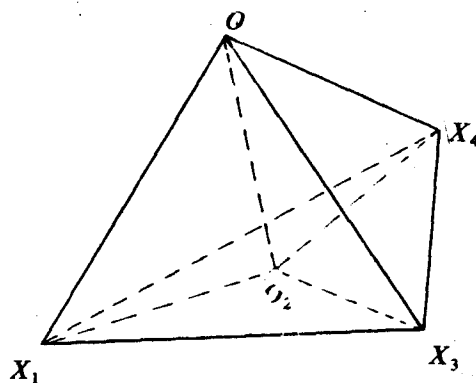


Fig. 2

## References

- [1] Ren Hong, Wang, The Structural Characterization and Interpolation for Multivariate Splines, *Acta Math. Sinica*, 18(1975), 90—105.
- [2] R. H. Wang, On the analysis of multivariate splines in the case of arbitrary partition, *Scientia Sinica, Math. I*, (1979), 215—226.
- [3] R. H. Wang, On the analysis of multivariate splines in the case of arbitrary partition II, Higher dimensional spline, *Numer. Math. J. Chinese Univ.* 2(1980), 78—81.
- [4] R. H. Wang, The dimension and basis of spaces of multivariate splines, *J. Comput. Appl. Math.*, 12 & 13(1985), 163—177.
- [5] Y. S. Chou, L. Y. Su, and R. H. Wang, The dimension of bivariate spline spaces over triangulations, In: W. Schempp and K. Zeller, eds. *Multivariate Approx. Th. III*, Birkhäuser, Basel, 1985, 71—83.
- [6] W. Dahmen and C. A. Micchelli, Recent progress on multivariate splines, *Approximation Theory IV*, Academic Press, New York, 1983, 27—121.
- [7] C. de Boor, Splines as linear combinations of B-splines, *Approximation Theory II*, Academic Press, New York, 1976, 1—47.
- [8] C. de Boor and K. Höllig, Bivariate box splines and smooth pp functions on a three direction mesh, *J. Comput. Appl. Math.*, 9(1983), 13—28.
- [9] A. Ženišek, Polynomial approximation on tetrahedrons in the finite element method, *J. Approx. Theory*, 7(1973), 334—351.
- [10] P. Alföldi, A trivariate Clough-Tocher scheme for tetrahedral data, *Computer Aided Geometric Design*, 1(1984), 169—181.
- [11] X. Q. Shi, S. M. Wang, W. B. Wang, and R. H. Wang, The  $C^1$ -quadratic spline space on triangulation, Research Report, Dept. Math. and Inst. Math. Jilin University No. 86004, 1986.