

On n -Dimensional Matrix Groups*

Jin Bai Kim and Alphonse Baartmas

(Dept. Math., West Virginia Univ.

Morgantown, W. V. 26506, U. S. A.)

Abstract An $n \times m$ matrix $A = \{a_{ij}\}$ will be called a 2-dimensional matrix of order n . We shall study groups of $2m$ -dimensional matrices of order n over a field of characteristic 0 with respect to an associative matrix product and we obtain the dimensions of such matrix groups.

Introduction There are several papers on n -dimensional matrices (cf [3, 4, 5, 6, 7]). Sokolov [7] is significant. Oldenburger [6] considered determinants of n -dimensional matrices. We describe some of the results of this paper. Let R, C , and H denote respectively the real number field, the complex number field and the field of the real quaternions. Let $M_{2m, n}(F)$ denote the set of all $2m$ -dimensional matrices of order n over a field $F \in \{R, C, H\}$. In $M_{2m, n}(F)$ there is an associative matrix product (see [5]) and under this matrix product $M_{2m, n}(F)$ forms a matrix group (and ring). We consider $M_{m, n}(F)$ as a vector space and we define an inner product $\langle X, Y \rangle$ for X, Y in $M_{m, n}(F)$. Then we can have a matrix group $S(2m, n, F) = \{A \in M_{2m, n}(F) : \langle XA, YA \rangle \text{ for all } X, Y \in M_{m, n}(F)\}$. If G is a group, its dimension is the dimension of the vector space $T(G)$ of the tangent vectors to G at the identity I . To get the dimension of the group $S(2m, n, F) = S(F)$ we need $T(S(F))$. We shall prove that $T(S(F)) = \text{So}(2m, n, F) = \{A, \in M_{2m, n}(F) : A + A^T = 0\}$, where A^T denotes the transpose and conjugate matrix of A . We find the dimension of $T(S(F))$, the vector space over the real numbers R , using a method of 'one parameter subgroups'.

1. A Matrix product and an Inner Product of Two Vectors

We begin with the following definitions.

Definition 1^[5] Let $A = (a_{i_1 i_2 \dots i_{2m}})$ and $B = (b_{i_1 i_2 \dots i_{2m}})$ be two matrices in $M_{2m, n}(F)$. We define a matrix product $AB = C = (c_{i_1 i_2 \dots i_{2m}})$ as follows:

$$c_{i_1 i_2 \dots i_{2m}} = \sum_{t_1=1}^n \sum_{t_2=1}^n \dots \sum_{t_m=1}^n a_{i_1 i_2 \dots i_m t_1 t_2 \dots t_m} b_{t_1 t_2 \dots t_m i_{m+1} \dots i_{2m}}$$

Note that this matrix product is associative^[5] and under this matrix product,

* Received Sept. 22, 1987.

$M_{2m,n}(F)$ forms a semigroup (and a ring).

Definition 2 The inner product of two vectors $X = (x_{ij\dots k})$ and $Y = (y_{ij\dots k})$ in $M_{m,n}(F)$ is defined as follows:

$$\langle X, Y \rangle = \sum_{t_1=1}^n x_{t_1 t_2 \dots t_m} \overline{y_{t_1 t_2 \dots t_m}} \quad (i = 1, 2, \dots, n)$$

where \overline{y} denotes the conjugate of $y \in C$ or $y \in H$.

We list the following two lemmas without proofs.

Lemma 1 The inner product $\langle X, Y \rangle$ of two vectors X and Y in $M_{m,n}(F)$ has the following properties.

- (i) $\langle X, Y+Z \rangle = \langle X, Y \rangle + \langle X, Z \rangle$, $\langle X+Y, Z \rangle = \langle X, Z \rangle + \langle Y, Z \rangle$ for all X, Y , and $Z \in M_{m,n}(F)$.
- (ii) $a\langle X, Y \rangle = \langle aX, Y \rangle$ and $\langle X, Y \rangle \overline{a} = \langle X, aY \rangle$ for all $a \in F$ and $X, Y \in M_{m,n}(F)$.
- (iii) $\langle \overline{X}, Y \rangle = \langle Y, X \rangle$ for all $X, Y \in M_{m,n}(F)$.
- (iv) $\langle X, Y \rangle \geq 0$ and $\langle X, X \rangle = 0$ iff $X = 0$.

Lemma 2 For any $X, Y \in M_{m,n}(F)$ and $A \in M_{2m,n}(F)$, we have that $\langle XA, Y \rangle = \langle X, YA^T \rangle$.

From now on F denotes a field in $\{R, C, H\}$. We prove the following theorem.

Theorem 3 Let $S(2m, n, F) = \{A \in M_{2m,n}(F) : \langle XA, YA \rangle = \langle X, Y \rangle \text{ for all } X, Y \in M_{m,n}(F)\}$. Then $S(2m, n, F)$ is a group.

Proof Let $A = (a_{ij\dots k})$, $B = (b_{ij\dots k}) \in S(2m, n, F)$. Then we see that $\langle XAB, YAB \rangle = \langle XA, YA \rangle = \langle X, Y \rangle$ for all $X, Y \in M_{m,n}(F)$, and hence $AB \in S(2m, n, F)$. We know that there exists $I = (x_{i_1 i_2 \dots i_{2m}})$, which is defined by (see [4]).

$$x_{i_1 i_2 \dots i_{2m}} = \begin{cases} 1 & \text{if } (i_1 i_2 \dots i_m) = (i_{m+1} i_{m+2} \dots i_{2m}), \\ 0 & \text{otherwise,} \end{cases}$$

such that $XI = IX = X$ and $AI = IA = A$ for all $X \in M_{m,n}(F)$ and $A \in M_{2m,n}(F)$. Thus

$I \in S(2m, n, F)$. We use $I = (\delta_{i_1 i_2 \dots i_m}^{i_{m+1} i_{m+2} \dots i_{2m}})$ for the identity I , where δ denotes the Kro-

necker's delta. Let $e_{i_1 i_2 \dots i_m}$ be a member of $M_{m,n}(F)$ whose $(i_1 i_2 \dots i_m)$ -entry is 1 and others are zero. We consider $\langle e_{i_1 i_2 \dots i_m} A, e_{j_1 j_2 \dots j_m} A \rangle$.

We first see that

$$\langle e_{i_1 i_2 \dots i_m} A, e_{j_1 j_2 \dots j_m} A \rangle = \delta_{i_1 i_2 \dots i_m}^{j_1 j_2 \dots j_m},$$

and also see that

$$\begin{aligned} \langle e_{i_1 i_2 \dots i_m} A, e_{j_1 j_2 \dots j_m} A \rangle &= \langle a_{i_1 i_2 \dots i_m 11 \dots 1}, \dots, a_{i_1 i_2 \dots i_m k_1 k_2 \dots k_m}, \dots, a_{i_1 i_2 \dots i_m n n \dots n} \rangle, \\ &\quad \langle a_{j_1 j_2 \dots j_m 11 \dots 1}, \dots, a_{j_1 j_2 \dots j_m k_1 k_2 \dots k_m}, \dots, a_{j_1 j_2 \dots j_m n n \dots n} \rangle \rangle \\ &= \sum_{k_t=1}^n a_{i_1 i_2 \dots i_m k_1 k_2 \dots k_m} \overline{a_{j_1 j_2 \dots j_m k_1 k_2 \dots k_m}}, \quad (t = 1, 2, \dots, n). \end{aligned}$$

which is the $(i_1 i_2 \dots i_m j_1 j_2 \dots j_m)$ -entry of AA^T . Hence this entry must be 1 if $i_p =$

j_p ($p=1, 2, \dots, m$) or 0 if $i_p \neq j_p$.

Therefore $AA^T = I$. We can also see that $A^T A = I$. Thus $A^{-T} = A^{-1}$. Now we see that $\langle XA^{-1}, XA^{-1} \rangle = \langle XA^{-1}A, YA^{-1}A \rangle = \langle X, Y \rangle$. This proves Theorem 3. We may call $S(2m, n, F)$ an orthogonal group.

Note Referring the identity I in the proof of Theorem 3, we define $GL(2m, n, F) = \{A \in M_{2m, n}(F) : AA^{-1} = I\}$ as the general linear group in $M_{2m, n}(F)$.

2. Dimensions of Vector Spaces $So(2m, n, F)$.

In this section we compute dimensions of vector spaces $So(2m, n, F)$ over the real numbers R .

Definition 3 ^[1] We define $So(2m, n, F) = \{A \in M_{2m, n}(F) : A + A^T = 0\}$. A matrix A in $So(2m, n, F)$ is called a F -skew symmetric matrix.

Lemma 4 $So(2m, n, F)$ is a vector space over R .

Proof We see that the zero matrix 0 is in $So(2m, n, F)$. Let $A, B \in So(2m, n, F)$. Then we see that $(A+B) + (A+B)^T = 0$ and hence $A+B \in So(2m, n, F)$. We also see that $rA + (rA)^T = r(A + A^T) = 0$ for all $r \in R$. Therefore $rA \in So(2m, n, F)$. This proves the lemma.

$\dim V$ denotes the dimension of a vector space V (over R).

Theorem 5 (i) $\dim So(2m, n, R) = n^m(n^m - 1)/2$.

(ii) $\dim So(2m, n, C) = n^{2m}$.

(iii) $\dim So(2m, n, H) = n^m(2n^m + 1)$.

Proof We prove (i). To get the dimension of $So(2m, n, R)$ we must find a basis. Let $E_{i_1 i_2 \dots i_m j_1 j_2 \dots j_m}$ denote the matrix in $M_{2m, n}(R)$ whose entries are all zero except the $(i_1 i_2 \dots i_m j_1 j_2 \dots j_m)$ entry, which is 1, and the $(j_1 j_2 \dots j_m i_1 i_2 \dots i_m)$ entry, which is $-1((i_1 i_2 \dots i_m) \neq (j_1 j_2 \dots j_m))$. Then we see that $E_{i_1 i_2 \dots i_m j_1 j_2 \dots j_m} \in So(2m, n, R)$. We redefine these $E_{i_1 \dots i_m j_1 \dots j_m}$ only for $i_t < j_t$, it is easy to see that they form a basis for $So(2m, n, R)$, and it is not difficult to count that there are $(n^m - 1) + (n^m - 2) + \dots + 1 = n^m(n^m - 1)/2$ of them. This proves that $\dim So(2m, n, R) = n^m(n^m - 1)/2$.

For (ii), Let $B = (b_{i_1 \dots i_m j_1 \dots j_m})$ be a matrix in $So(2m, n, C)$. Then $B + B^T = 0$, from which we get that $b_{i_1 i_2 \dots i_m j_1 j_2 \dots j_m} + \overline{b_{j_1 j_2 \dots j_m i_1 i_2 \dots i_m}} = 0$ for any $(i_1 i_2 \dots i_m j_1 j_2 \dots j_m)$ entry of B . If $b_{i_1 i_2 \dots i_m j_1 j_2 \dots j_m} = c + di$, then $\overline{b_{j_1 j_2 \dots j_m i_1 i_2 \dots i_m}} = -c - di$ and $b_{j_1 j_2 \dots j_m i_1 i_2 \dots i_m} = -c + di$. If $(i_1 i_2 \dots i_m) = (j_1 j_2 \dots j_m)$, then $c + di = -c + di$ and $c = 0$. Consequently, the number of elements consisting a basis is equal to $n^m + 2n^m(n^m - 1)/2 = n^{2m}$.

For (iii), letting $C = (c_{i_1 i_2 \dots i_m j_1 j_2 \dots j_m}) \in S(2m, n, H)$, we have that $C + C^T = 0$ and $c_{i_1 i_2 \dots i_m j_1 j_2 \dots j_m} + \overline{c_{j_1 j_2 \dots j_m i_1 i_2 \dots i_m}} = 0$ for any $(i_1 i_2 \dots i_m j_1 j_2 \dots j_m)$ entry of C . If $c_{i_1 i_2 \dots i_m j_1 j_2 \dots j_m} = x + yi + uj + vk$, then $\overline{c_{j_1 j_2 \dots j_m i_1 i_2 \dots i_m}} = -x - yi - uj - vk$ and $c_{j_1 j_2 \dots j_m i_1 i_2 \dots i_m} = -x + yi + uj + vk$. If $(i_1 i_2 \dots i_m) \neq (j_1 j_2 \dots j_m)$ then $x = 0$ and $c_{i_1 \dots i_m j_1 \dots j_m} = yi + uj + vk$. Consequently, the number of elements consisting a basis is equal to $3n^m + 4(n^m(n^m - 1)/2) = n^m(2n^m + 1)$.

This proves Theorem 5.

3. Curves in a Vector Space

We need the following definition.

Definition 4 Let V be a finite dimensional vector space. π is called a curve in V if $\pi: (a, b) \rightarrow V$ is a continuous function, where (a, b) is an open interval in \mathbb{R} . For $c \in (a, b)$, we say that π is differentiable at c if

$$\lim_{h \rightarrow 0} \frac{\pi(c+h) - \pi(c)}{h}$$

exists. When this limit exists, it is a vector in V . We denote it by $\pi'(c)$ and call the tangent vector to π at $\pi(c)$. Note that $M_{2m,n}(\mathbb{R})$, $M_{2m,n}(\mathbb{C})$ and $M_{2m,n}(\mathbb{H})$ are real vector spaces of dimensions n^{2m} , $2n^{2m}$ and $4n^{2m}$, respectively. If G is a matrix group in $M_{2m,n}(F)$, then a curve in G is a curve in $M_{2m,n}(F)$ with all values $\pi(t)$ for $t \in (a, b)$ lying in G . If π_1 and π_2 are curves such that $\pi_i: (a, b) \rightarrow G$ then the product curve is defined by $(\pi_1 \pi_2)(t) = \pi_1(t) \pi_2(t)$, for $t \in (a, b)$.

Theorem 6 Let G be a matrix group in $M_{2m,n}(F)$. Let T be the set of all tangent vectors $\pi'(0)$ to the curves $\pi: (-s, s) \rightarrow G$ with $\pi(0) = I$, the identity matrix of G . Then T is a subspace of $M_{2m,n}(F)$.

Proof Let $\pi_i'(0) \in T$ ($i = 1, 2$). Then $(\pi_1 \pi_2)(0) = I$, $(\pi_1 \pi_2)'(0) = \pi_1'(0) \pi_2(0) + \pi_1(0) \pi_2'(0) = \pi_1'(0) + \pi_2'(0) \in T$, and hence T is closed under vector addition. Let $\pi_1'(0) \in T$ and $c \in \mathbb{R}$. Define $\pi_2(t) = \pi_1(ct)$. Then we see that $\pi_2(0) = \pi_1(0) = I$ and $\pi_2'(0) = c\pi_1'(0)$ since $\pi_2'(t) = c\pi_1'(t)$. This proves Theorem 6.

Definition 5 ([1, p. 37]) If G is a matrix group, its dimension is the dimension of the vector space $T(G)$ which is the set of all tangent vectors of G at I .

Let T be the set of all tangent vectors defined as in Theorem 6.

Theorem 7 If π is a curve through the identity, that is, $\pi(0) = I$, then $\pi'(0) \in T$ is a F -skew symmetric matrix in $\text{So}(2m, n, F)$.

Proof By differentiating both sides of $\pi(u)\pi^{-1}(u) = I$, we obtain that $\pi'(u)\pi^{-1}(u) + \pi(u)(\pi^{-1})'(u) = 0$ and $\pi'(0) + (\pi^{-1})'(0) = 0$, which shows that $\pi'(0)$ is F -skew symmetric. This proves Theorem 7.

Corollary

- (i) $\dim S(2m, n, \mathbb{R}) \leq n^m(n^m - 1)/2$.
- (ii) $\dim S(2m, n, \mathbb{C}) \leq n^{2m}$.
- (iii) $\dim S(2m, n, \mathbb{H}) \leq n^m(2n^m + 1)$.

Proof By Theorem 3, $S(2m, n, F)$ is a matrix group. We see that $\dim S(2m, n, F) = \dim T(S(2m, n, F)) = \dim \{\pi'(0) : \pi(u) \in S(2m, n, F)\}$. Since $\pi'(0) \in \text{So}(2m, n, F)$, $\dim S(2m, n, F)$ can not exceed $\dim \text{so}(2m, n, F)$, $F \in \{\mathbb{R}, \mathbb{C}, \mathbb{H}\}$. This proves Corollary.

Let $\varphi: G_1 \rightarrow G_2$ be a homomorphism of matrix groups G_1 and G_2 . Since G_i are

in vector spaces, it is clear what it means for φ to be continuous. From now on homomorphism always means continuous homomorphism. This being so, a curve $\pi: (a, b) \rightarrow G_1$ gives a curve $\varphi\pi: (a, b) \rightarrow G_2$ by $(\varphi\pi)(u) = \varphi(\pi(u))$ in G_2 .

Definition 6 A homomorphism $\varphi: G_1 \rightarrow G_2$ of matrix groups is smooth if for every differentiable curve π in G_1 , $\varphi\pi$ is differentiable. This definition is needed in the next section.

4. A One Parameter Subgroup in a Matrix Group

Using Definition 6, we define 'one parameter subgroup' as follows.

Definition 7 A one parameter subgroup π in a matrix group $G (\subset M_{2m, n}(F))$ is a smooth homomorphism $\pi: R \rightarrow G$ with $\pi(s+t) = \pi(s)\pi(t)$ for all s and t in R .

Note that it suffices to know π on some open neighborhood U of 0 in R . For $x \in R$, some $\frac{1}{n}x \in U$ and $\pi(x) = (\pi(\frac{1}{n}x))^n$.

Example Let $A \in M_{2m, n}(F)$. Then $\pi(u) = e^{uA}$ is a one parameter subgroup of $GL(2m, n, F)$. (We often use t instead of u).

Theorem 8 π is a one parameter subgroup of $GL(2m, n, F)$ iff there exists A in $M_{2m, n}(F)$ such that $\pi(t) = e^{tA}$ with $\pi'(0) = A$.

Proof Suppose π is a one parameter subgroup of $GL(2m, n, F)$, and let $\log \pi(t) = \lambda(t)$. Then λ is a curve in $M_{2m, n}(F)$ with $\pi(t) = e^{\lambda(t)}$. Set $\lambda'(0) = A$. Then for any fixed t_0 ,

$$\begin{aligned} \lambda'(t_0) &= \lim_{h \rightarrow 0} \frac{\lambda(t_0 + h) - \lambda(t_0)}{h} = \lim_{h \rightarrow 0} \frac{\log \pi(t_0 + h) - \log \pi(t_0)}{h} \\ &= \lim_{h \rightarrow 0} \frac{\log \pi(t_0)\pi(h) - \log \pi(t_0)}{h} = \lim_{h \rightarrow 0} \frac{\log \pi(h)}{h} = \lambda'(0) = A. \end{aligned}$$

This means that $\lambda'(t)$ is independent of t . Hence, $\lambda(t) = tA$ which implies that $\lambda(t)$ is a line through $0 \in M_{2m, n}(F)$ and $\pi(t) = e^{tA}$. Conversely, suppose that there exists λ in $M_{2m, n}(F)$ such that $\pi(t) = e^{tA}$ with $\pi'(0) = A$. Then

$$\pi(t) = I + A + \frac{t^2 A^2}{2!} + \frac{t^3 A^3}{3!} + \dots, \quad \pi(0) = I, \quad \pi(-t) = I - tA + \frac{t^2 A^2}{2!} - \dots$$

and $\pi(t)\pi(-t) = I$. This means that $\pi(t) \in GL(2m, n, F)$. Finally, we see that $\pi(t+s) = \pi(t)\pi(s)$. This proves Theorem 8. This theorem shows that any tangent vector to $GL(2m, n, F)$ is the derivative at 0 of some one parameter subgroup.

Lemma 9 If $A \in \text{So}(2m, n, F)$, then $e^{uA} e^{(\overline{uA})^t} = I$, where $u \in R$.

Proof By the assumption, $A + A^{-t} = 0$ for $A \in \text{So}(2m, n, F)$. Then we see that

$$e^{uA} e^{(\overline{uA})^t} = I + u(A + A^{-t}) + \dots + u^n \left(\sum_{k=0}^n \frac{A^{n-k} (A^{-t})^k}{(n-k)! k!} \right) + \dots = \sum_{n=0}^{\infty} I_n u^n,$$

where

$$I_0 = I, \quad I_n = \sum_{k=0}^n \frac{A^{n-k} (A^{-t})^k}{(n-k)! k!}.$$

We prove that $I_n = 0$ for $n > 1$ because $I_1 = 0$. We prove it by mathematical

induction on n . We assume that we have proven that $I_t = 0$ for all $t < n$, where n is a fixed integer greater than 1. We define

$$\binom{k}{n} = \frac{(n-1)(n-2)\cdots(n-k)}{n!k!} \quad \text{and} \quad I(k) = \frac{A^{n-k}(A^{-1})^k}{(n-k)!k!}.$$

Then we see that

$$\begin{aligned} I(n) &= \sum_{k=0}^n I(k) \sum_{k=0}^m I(k) + I(m+1) + I(m+2) + \cdots + I(n) \\ &= \binom{m}{n} A^{n-m} (A^{-1})^m + I(m+1) + I(m+2) + \cdots + I(n) = \sum_{k=0}^{n-1} I(k) + I(n) \\ &= \frac{(n-1)!}{n!(n-1)!} A (A^{-1})^{n-1} + \frac{(A^{-1})^n}{n!} = \frac{1}{n!} (A + (A^{-1})) (A^{-1})^{n-1} = 0, \end{aligned}$$

that is, $I(n) = 0$. Consequently, $e^{uA} e^{(\overline{uA})^t} = I = e^0$. This proves Lemma 9.

Theorem 10 Let A be a tangent vector to the orthogonal group $S(2m, n, F)$. Then there exists a unique one parameter subgroup π in $S(2m, n, F)$ such that $A = \pi'(0)$.

Proof We have that $A = \pi'(0)$ for some curve π in $S(2m, n, F)$ since A is a tangent vector to the orthogonal group $S(2m, n, F)$. For any $u \in (-t_0, t_0)$ we have $\pi(u) \overline{\pi(u)}^t = I$ and $\pi'(u) \overline{\pi(u)}^t + \pi(u) (\overline{\pi(u)}^t)' = 0$. Letting $u = 0$, we obtain that $\pi'(0) + (\pi^{-1})'(0) = 0$ which is equivalent to $A + A^{-1} = 0$. Thus $A \in \text{So}(2m, n, F)$. Now $\pi(u) = e^{uA}$ is a one-parameter subgroup of $\text{GL}(2m, n, F)$ by Theorem 8, but it lies in $S(2m, n, F)$ because $\pi(u) \overline{\pi(u)}^t = e^{uA} e^{u(A^{-1})} = I$ by Lemma 9. This proves Theorem 10.

Now we obtain the following proposition.

Proposition 11 ([1, p. 53—p. 54]).

$$(i) \quad \dim S(2m, n, R) = \dim \text{So}(2m, n, R) = \frac{n^m(n^m - 1)}{2}.$$

$$(ii) \quad \dim S(2m, n, C) = \dim \text{So}(2m, n, C) = n^{2m}.$$

$$(iii) \quad \dim S(2m, n, H) = \dim \text{So}(2m, n, H) = n^m(2n^m + 1).$$

Proof It follows from Definition 7, Theorem 5 and Theorem 10.

5. A Problem

To pose a problem we need a definition.

Definition 8 ([1, p. 93 and p. 127]) A k -torus is the cartesian product of k circle groups. The rank of a matrix group G is the dimension of a maximal torus in G .

Problem Let $F \in \{R, C, H\}$. Find ranks of $S(2m, n, F)$.

References

- [1] M. L. Curtis, *Matrix groups*, Springer-Verlag, 1979.
- [2] E. B. Davies, *One parameter semigroups*, Academic Press, 1980.
- [3] R. Kaneiwa, *N-dimensional matrices and n th order invariant forms*, (Japanese), *Surikaiseki K. K.* 274(1976), 83—97: MR58—10955.
- [4] Jin B. Kim and James E. Dowdy, *Determinants of n -dimensional matrices*, *J. Korean Math. Soc.* 17(1980), 63—68: MR81k—15006.
- [5] Jin B. Kim and James E. Dowdy, *On n -dimensional idempotent matrices*, *Publications de L'Institut Mathematique, Nouvelle Serie*, tome 33—47(1983), 119—122. MR85e—15021.
- [6] R. Oldenburger, *Higher dimensional determinants*, *Amer. Math. Monthly* 47(1940), 25—33: MR1—194.
- [7] N. P. Sokolov, *Spatial matrices and their applications* (Russian), *Gosudarstv. Izdat. Fiz-Mat. Lit.*, Moscow, 1960, 300pp: MR14—A122.