

## Global Attractor of a Spatially Discretized Reaction Diffusion System with Hamiltonian Structure \*

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In recent years there has been a growing interest on discrete models, see e.g.[1].[2]. We consider a reaction diffusion equation which space-independent system is a Hamilton system with one degree of freedom:

$$\begin{cases} u_t = u_{xx} + v, & 0 < x < 1, t > 0, \\ v_t = v_{xx} - u + u^2, & 0 < x < 1, t > 0, \\ u(0, t) = u(1, t) = 0, v(0, t) = v(1, t) = 0, & t > 0, \\ u(0, x) = u_0, v(0, x) = v_0, & 0 < x < 1. \end{cases} \quad (1)$$

For Hamilton structured reaction diffusion systems, the local dynamics is structurally unstable while most conditions imposed on gradient-structured system are not gradient-structured equation:  $u_t = \gamma \Delta u - f(u)$  with five restrictions on function ([1]), Huang and Lu studied the existence of global attractor of Henon-Heiles hamilton system, ([2]) but functions  $f(v) = v$  and  $g(u) = -u + u^2$  in system (1) do not satisfy the five restrictions on the functions.

Let us discretize spatial variable of (1). The discretized negative Laplacian operator  $-\Delta$  with Dirichlet boundary condition by using the finite difference is set to be  $A$ ,

$$A = \begin{pmatrix} 2 & -1 & 0 & \cdots & \cdots & 0 \\ -1 & 2 & -1 & \cdots & \cdots & 0 \\ 0 & -1 & 2 & \ddots & & \vdots \\ \vdots & \vdots & & \ddots & \ddots & \vdots \\ & & & & -1 & 2 & -1 \\ 0 & \cdots & \cdots & 0 & -1 & 2 \end{pmatrix}, \quad \begin{aligned} u(t) &= (u_1, u_2, \cdots, u_{m-1})^T, \\ v(t) &= (v_1, v_2, \cdots, v_{m-1})^T, \\ u^2(t) &= (u_1^2, u_2^2, \cdots, u_{m-1}^2)^T, \\ u_0 &= (u_1^0, u_2^0, \cdots, u_{m-1}^0)^T, \\ v_0 &= (v_1^0, v_2^0, \cdots, v_{m-1}^0)^T, \end{aligned}$$

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where  $u_i(t) = u(\frac{i}{m}, t)$ ,  $v_i(t) = v(\frac{i}{m}, t)$ ,  $i = 1, 2, \dots, m-1$ , and  $A$  is an  $(m-1) \times (m-1)$  symmetric and positive definite matrix. And its eigenvalues satisfying:  $\frac{1}{c_p^2} \leq \lambda_i \leq \frac{c_0}{h^2}$ , ( $mh = 1$ )

With the above nations, the spatially finite difference discretized version of (1) can be written by:

$$\begin{cases} u_t = -m^2 Au + v, \\ v_t = -m^2 Av - u + u^2, \\ u(0) = u_0, v(0) = v_0, \end{cases} \quad (2)$$

and we further introduce  $P(t) = (u, v)^T$ ,  $P_i(t) = (u_i, v_i)^T$ ,  $u_i, v_i \in R^{m-1}$ ,  $B = \text{diag}(m^2 A, m^2 A)$ . Then, the matrix  $B$  is positive definite, and we define inner products and norms respectively:

$$\begin{aligned} (u, v) &= u^T v, \quad |u|^2 = (u, u); \quad (u, v)_A = u^T A v, \\ \|u\|_A^2 &= (u, u)_A, \quad (P_1, P_2) = P_1^T P_2, \quad |P|^2 = (P, P), \\ (P_1, P_2)_B &= P_1^T B P_2, \quad \|P\|_B^2 = (P, P)_B. \end{aligned}$$

It is easy to obtain the following lemma:

**Lemma 1** 1)  $|P|^2 = |u|^2 + |v|^2$ ; 2)  $\|P\|_B^2 = m^2(\|u\|_A^2 + \|v\|_A^2)$ ;

3)  $|u| \leq c_p \|u\|_A$ ,  $\|u\|_A^2 \leq \frac{c_0}{h^2} |u|^2$ ;

4)  $\|u\|_A \leq c_p |Au|$ ,  $|Au|^2 \leq \frac{c_0}{h^2} \|u\|_A^2$ .

**Theorem 1**  $\Omega = \{(u, v)^T \in R^{2m-2}, |u|^2 + |v|^2 \leq 2c, 0 < c < \frac{1}{2} \frac{m^4}{c_p^4}\}$  is an invariant region for (2).

We denote  $E_0 = L^2(\Omega, |\cdot|)$ ,  $E_1 = L^2(\Omega, \|\cdot\|_B)$ . Similarly, we can obtain the theorems:

**Theorem 2** For any  $P_0 = (u_0, v_0)^T \in E_0$ , there is a unique global solution  $P(t) = (u, v)^T$  for (2), the semigroup  $\{S(t)\}_{t \geq 0}$  defined by  $S(t)P_0 = P(t)$ , ( $t \geq 0$ ) is continuous in  $E_0$ .

**Theorem 3** There exist constants  $\rho_1$  and  $\rho_2$  such that  $B_1 = \{P \in E_0, |P| \leq \rho_1\}$  and  $B_2 = \{P \in E_1, \|P\|_B \leq \rho_2\}$  are absorbing sets for the semigroup  $\{S(t)\}_{t \geq 0}$  in  $E_0$  and  $E_1$  respectively.

**Theorem 4** There exist maximal attractors  $G_0$  and  $G_1$  in  $E_0$  and  $E_1$  respectively,  $G_0 = \omega(B_0)$ ,  $G_1 = \omega(B_1)$  where  $B_0, B_1$  are the bounded set in  $E_0$  and  $E_1$  respectively.  $G_0$  and  $G_1$  are connected.

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