On Decision Tree Complexity of Boolean Function and Yao's Question *

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Abstract: A Boolean function $f(x_1, x_2, \dots, x_n)$ is said to be elusive, if every decision tree algorithm computing f must examine all n variables in the worst case. In 1988, A.C.C. Yao introduced a question: Is any nontrivial monotone Boolean function that is invariant under the transitive act of group $C_m \times C_n$ elusive? The positive answer to this question supports the famous Rivest-Vuillemin conjecture on decision tree complexity. In this paper, we shall partly answer this question.

Key words: Boolean function; decision tree; complexity; Rivest-Vuillemin conjecture.

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1. Introduction

It is well known that a tree is a connected graph without cycle. A rooted tree is a tree with a special vertex named root. Let T be a tree, when every edge of T is given a direction, we get a directed tree. In a directed tree, for any vertex V, the number of directed edges into V is called indegree of V, and the number of directed edges out of V is called outdegree of V.

A rooted binary tree T is a directed tree in which the indegree of the root vertex is 0 and the indegree of other vertices is 1, and the outdegree of any vertex is either 2 or 0. The vertices whose outdegree is 0 are called leaves of T. If directed edge $(x,y) \in T$, then x is called father of y, and y is called a child of x. Clearly, in a rooted binary tree, each vertex has two children but any leaf has no child.

A Boolean function is a function whose variable values and function value all are in $\{0,1\}$. In general, Boolean function is represented by Boolean operations: conjunction \land , disjunction \lor and negation \neg . For example,

$$f(x,y) = ((\neg x) \wedge y) \vee (x \wedge (\neg y)).$$

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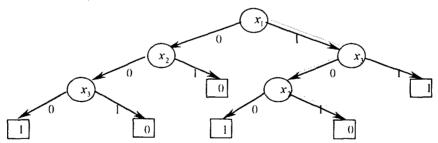
For simplicity, we usually write xy for $x \wedge y$, x + y for $x \vee y$ and \bar{x} for $\neg x$. So, above Boolean function can be written as

$$f(x,y)=\bar{x}y+x\bar{y}.$$

An assignment for a Boolean function is a mapping from its variables to $\{0,1\}$, each variable gets exactly one value from an assignment. For a Boolean function of n variables, an assignment can be seen as a binary string of length n, i.e., a string in $\{0,1\}^n$. An assignment x of Boolean function f(x) is called a truth-assignment if f(x) = 1, and false-assignment if f(x) = 0. We denote by truth(x) and false(x) respectively the sets of variables taking value 1 and taking value 0 in the assignment x.

For two assignments of a Boolean function $f(x_1, x_2, \dots, x_n)$, say, $x = (x_1, x_2, \dots, x_n)$ and $y = (y_1, y_2, \dots, y_n)$, if $x_i \leq y_i$ for all i, then we write $x \leq y$. A Boolean function f(x) is increasing if f(x) = 1 and $x \leq y$ imply f(y) = 1, decreasing if f(y) = 1 and $x \leq y$ imply f(x) = 1, monotone if it is either increasing or decreasing. f(x) is nontrivial if it is not a constant function.

A Boolean function f can also be represented by a rooted binary tree that is so-called decision tree of f. A decision tree of a Boolean function f is a rooted binary tree, whose non-leaf vertices are labeled by its variables, and leaves are labeled by 0 and 1. Edges of this binary tree are also labeled by 0 and 1 such that edges from a non-leaf vertex to its two children are labeled by 0 and 1 respectively, and any variable appears at most once in a path from the root to any leaf. Given an assignment to the variables of a Boolean function, we can compute the function value by its decision tree as follows: starting from the root, we look at its label. If its label is x_i , then we make a decision according to the value of x_i to decide where we go. If $x_i = 0$, then we go to the next vertex along the edge with label 0; if $x_i = 1$, then we go to the next vertex along the edge with label 1. Once a leaf is reached, the function value for the given assignment is obtained. For example, a decision tree of $f(x_1, x_2) = x_1x_3 + \bar{x}_2\bar{x}_3$ is as follows:



A path is marked in the decision tree for computing f(1,1,0). Since the leaf is labeled by 0, we have f(1,1,0) = 0.

The decision tree representation of Boolean function is very useful in computer science. In fact, a decision tree of f gives a procedure (or say, algorithm) to compute the function value. The computation time depends on the length of path that is the number of variables on the path. The depth of a decision tree is the maximum length of all paths from root to leaves. Actually, the depth of a decision tree is exactly the number of queries that the algorithm must make for computing f in the worst case. In other words, the depth of a decision tree shows the computational complexity of the decision tree algorithm.

A Boolean function f may have a lot of decision trees. We denote by D(f) the minimum depth of all decision trees for computing f. D(f) is called the decision tree complexity of f. Clearly, $D(f) \leq n$ when f has n variables. If D(f) = n, then f is said to be elusive.

It is known that decision tree complexity as an important measure of complexity is closely related to several other combinatorial and complexity measures, e.g., it is related to the certificate complexity (see [1]), to the block sensitivity ([2]), and to the packing of graphs ([3]). Furthermore, its logarithm is equal, up to a constant factor, to the time to compute f on a CREW PRAM ([2]).

A group G of permutations on $\{1,2,\dots,n\}$ is called *transitive* if for any $i,j \in \{1,2,\dots,n\}$, there exists $\sigma \in G$ such that $\sigma(i) = j$. Let $f(x_1, x_2, \dots, x_n)$ be a Boolean function and G be a group of permutations on $\{1,2,\dots,n\}$. $f(x_1,x_2,\dots,x_n)$ is said to be *invariant* under group G if for any $\sigma \in G$,

$$f(x_1,x_2,\cdots,x_n)=f(x_{\sigma(1)},x_{\sigma(2)},\cdots,x_{\sigma(n)}).$$

A Boolean function $f(x_1, x_2, \dots, x_n)$ is said to be weakly symmetric if there exists a transitive permutation group G on $\{1, 2, \dots, n\}$ such that $f(x_1, x_2, \dots, x_n)$ is invariant under G.

In last twenty years, many researchers have paid their efforts to decision tree complexity of Boolean function ([3] \sim [13]). Especially, the following conjecture is one of focuses on which people concerned.

Rivest-Vuillemin Conjecture Every nontrivial monotone weakly symmetric Boolean function is elusive.

Authors of [10] proved that Rivest-Vuillemin Conjecture is true when n is a prime power. In general case, this conjecture is still open. In [12] A.C.C. Yao showed that any nontrivial monotone Boolean function which is invariant under the transitive act of cyclic group C_m must be elusive, and queried whether the analogous result is true for Boolean function which is invariant under the transitive act of group $C_m \times C_n$. This question is called Yao's question. Obviously, the positive answer to this question partly supports Rivest-Vuillemin Conjecture. In this paper, we make a discussion to decision tree complexity of Boolean function, mainly around Yao's question.

2. Preliminary

An abstract complex Δ on a finite set X is a family of subsets of X, such that if A is a member of Δ , so is every subset of A. Each member of abstract complex Δ is called a face of Δ . A maximal face of abstract complex Δ is a face that is not contained by another face. A free face is a non-maximal face that is contained by only one maximal face. An elementary collapse is an operation that deletes a free face together with all faces containing it. An abstract complex Δ is collapsible if it can be elementarily collapsed to the empty abstract complex.

The complex Δ_f of monotone Boolean function $f(x_1, x_2, \dots, x_n)$ is an abstract complex that is defined as follows:

if
$$f(x)$$
 is monotone increasing, then $\Delta_f = \{ false(x) | f(x) = 1 \};$

if f(x) is monotone decreasing, then $\Delta_f = \{ \operatorname{truth}(x) | f(x) = 1 \}$.

Since f is monotone, every subset of face A of Δ_f is still in Δ_f . Hence, abstract complex Δ_f is well defined. Each vertex of Δ_f is a variable of f.

The Euler characteristic of an abstract complex Δ is defined by

$$\chi(\Delta) = \sum_{A \in \Delta, A \neq \phi} (-1)^{|A|-1} = \sum_{A \in \Delta} (-1)^{|A|-1} + 1.$$

In particular, $\chi(\phi) = 1$ and $\chi(\{\phi\}) = 0$.

A permutation σ on the vertex set of abstract complex Δ is called an automorphism of Δ if for any face A of Δ , $\sigma(A) = {\sigma(a)|a \in A}$ is still a face of Δ . Let G be a group of automorphisms on Δ , an orbit of G is a minimal subset of vertices of Δ such that G takes no vertex out of it. It is obvious that G has only one orbit on Δ if and only if G is transitive on vertices of Δ .

Denote

$$\Delta^G = \{\{H_1, \cdots, H_k\} | H_1, \cdots, H_k \text{ are orbits of } G, \text{ and } H_1 \cup \cdots \cup H_k \in \Delta\} \cup \{\phi\}.$$

Clearly, Δ^G is also an abstract complex.

For an abelian group G (here either Z or Z_p , p is a prime), we may consider the homology groups with coefficients in G. Say a complex Δ is G-acyclic if the homology groups of Δ are

$$H_0(\Delta, G) = G, \quad H_i(\Delta, G) = 0, \quad i > 0,$$

where $H_i(\Delta, G)$ denotes the *i*-dimensional homology group of Δ with respect to G.

3. Main results

The following lemmas set up a bridge between algebraic topology and elusiveness.

Lemma 1^[7] Every collapsible abstract complex is \mathbb{Z}_p -acyclic.

Lemma 2^[7] If Δ_f is not collapsible, then f is elusive.

Lemma 3^{[14][15]} Assume that G is a group of automorphisms on the finite Z_p -acyclic complex Δ . If there exists a normal subgroup G_1 of G such that $|G_1| = p^k$ (p is a prime and kis a positive integer) and the quotient group G/G_1 is cyclic, then $\chi(\Delta^G) = 1$.

Lemma 4 Let $f(x_1, x_2, \dots, x_n)$ be a nontrivial monotone Boolean function, and G be a group of automorphisms on Δ_f . If there exists a normal subgroup G_1 of G such that (1) $|G_1| = p^k$ (p is a prime and k is a positive integer), (2) the quotient group G/G_1 is cyclic, and (3) $\chi(\Delta_f^G) \neq 1$, then f is elusive.

Proof Suppose to the contrary that $f(x_1, x_2, \dots, x_n)$ is not elusive. By Lemma 1 and Lemma 2, Δ_f is Z_p -acyclic. By Lemma 3, this result, combining the conditions of lemma, implies that $\chi(\Delta_f^G) = 1$, which contradicts the assumption of current lemma. \square

Suppose that $f(x_1, x_2, \dots, x_n)$ is a nontrivial monotone Boolean function, and $n = n_1 \cdot n_2$. Label all variables by elements in $Z_{n_1} \times Z_{n_2}$, say,

$$(x_1,x_2,\cdots,x_n)=(x_{11},\cdots,x_{1n_2},x_{21},\cdots,x_{2n_2},\cdots,x_{n_11},\cdots,x_{n_1n_2}).$$

Denote by G_{n_1} and G_{n_2} respectively a group of permutations on $\{1, 2, \dots, n_1\}$ and $\{1, 2, \dots, n_2\}$ $G_{n_1} \times G_{n_2}$ is the direct product of G_{n_1} and G_{n_2} acting on $Z_{n_1} \times Z_{n_2}$. For any $(\sigma, \tau) \in G_{n_1} \times G_{n_2}$ and any $(i, j) \in Z_{n_1} \times Z_{n_2}$,

$$(\sigma,\tau)(i,j)=(\sigma(i),\tau(j)).$$

Clearly, $G_{n_1} \times G_{n_2}$ naturally induces a group of permutations on the variables of

$$f(x_{11},\cdots,x_{1n_2},x_{21},\cdots,x_{2n_2},\cdots,x_{n_11},\cdots,x_{n_1n_2}).$$

 $f(x_1, x_2, \dots, x_n)$ is said to be invariant under $G_{n_1} \times G_{n_2}$ if

$$f(x_{11}, \cdots, x_{1n_2}, x_{21}, \cdots, x_{2n_2}, \cdots, x_{n_11}, \cdots, x_{n_1n_2})$$

$$= f(x_{\sigma(1)\tau(1)}, \cdots, x_{\sigma(1)\tau(n_2)}, x_{\sigma(2)\tau(1)}, \cdots, x_{\sigma(2)\tau(n_2)}, \cdots, x_{\sigma(n_1)\tau(1)}, \cdots, x_{\sigma(n_1)\tau(n_2)})$$

for all $(\sigma, \tau) \in G_{n_1} \times G_{n_2}$.

Lemma 5 If $f(x_1, x_2, \dots, x_n)$ is invariant under $G_{n_1} \times G_{n_2}$, then $G_{n_1} \times G_{n_2}$ induces a group of automorphisms on Δ_f .

Proof Without loss of generality, suppose that $f(x_1, x_2, \dots, x_n)$ is decreasing. For any $(\sigma, \tau) \in G_{n_1} \times G_{n_2}$, we are going to show that (σ, τ) is an automorphism of complex

$$\Delta_f = \{ \operatorname{truth}(\boldsymbol{x}) | f(\boldsymbol{x}) = 1 \}.$$

Take arbitrarily a face $A = \{x_{i_1j_1}, \dots, x_{i_kj_k}\}$ of Δ_f . Assume the assignment corresponding to this face is $(a_{11}, a_{12}, \dots, a_{n_1n_2})$, i.e.,

$$f(a_{11}, a_{12}, \cdots, a_{n_1 n_2}) = 1$$

and

$$truth(a_{11}, a_{12}, \cdots, a_{n_1n_2}) = A.$$

Notice that

$$f(a_{\sigma^{-1}(1)\tau^{-1}(1)}, a_{\sigma^{-1}(1)\tau^{-1}(2)}, \cdots, a_{\sigma^{-1}(n_1)\tau^{-1}(n_2)}) = 1$$

since $f(x_1, x_2, \dots, x_n)$ is invariant under $G_{n_1} \times G_{n_2}$ and

$$(\sigma^{-1}, \tau^{-1}) \in G_{n_1} \times G_{n_2}$$
.

Moreover,

$$\begin{split} (\sigma,\tau)(A) &= \{x_{\sigma(i_1)\tau(j_1)}, \cdots, x_{\sigma(i_k)\tau(j_k)}\} = \{x_{\sigma(i)\tau(j)} | x_{ij} \in A\} \\ &= \{x_{\sigma(i)\tau(j)} | a_{ij} = 1\} = \{x_{ij} | a_{\sigma^{-1}(i)\tau^{-1}(j)} = 1\} \\ &= \operatorname{truth}(a_{\sigma^{-1}(1)\tau^{-1}(1)}, a_{\sigma^{-1}(1)\tau^{-1}(2)}, \cdots, a_{\sigma^{-1}(n_1)\tau^{-1}(n_2)}). \end{split}$$

Hence $(\sigma, \tau)(A)$ is still a face of Δ_f corresponding to assignment

$$(a_{\sigma^{-1}(1)\tau^{-1}(1)}, \cdots, a_{\sigma^{-1}(n_1)\tau^{-1}(n_2)}).$$

This shows that (σ, τ) is indeed an automorphism of Δ_f . The analogous deduction can be done when $f(x_1, x_2, \dots, x_n)$ is increasing. \square

Now we can prove the following main theorem.

Theorem 1 Let $f(x_1, x_2, \dots, x_n)$ be a nontrivial monotone Boolean function, and $n = n_1 \cdot n_2$. If f is transitively invariant under group $G_{n_1} \times G_{n_2}$, where G_{n_1} and G_{n_2} are defined as above, $|G_{n_1}|$ is equal to a power of prime and G_{n_2} is cyclic. Then $f(x_1, x_2, \dots, x_n)$ is elusive.

Proof Label all variables of $f(x_1, x_2, \dots, x_n)$ by elements in $Z_{n_1} \times Z_{n_2}$, and $G_{n_1} \times G_{n_2}$ acts on the variables as before. Denote $G = G_{n_1} \times G_{n_2}$. It is already shown in Lemma 5 that G is a group of automorphisms on Δ_f . It can be further checked that $G_{n_1} \times G_{n_2}$ has the following properties:

(1) Let $G_1 = \{(\sigma, 1) | \sigma \in G_{n_1}\}$. Then G_1 is a normal subgroup of G since for any $(\sigma, 1) \in G_1$ and $(\sigma_1, \tau_1) \in G$,

$$(\sigma_1, \tau_1)(\sigma, 1)(\sigma_1, \tau_1)^{-1} = (\sigma_1 \sigma \sigma_1^{-1}, 1) \in G_1$$

- (2) The quotient group G/G_1 is cyclic since $G/G_1\cong (G_{n_1}\times G_{n_2})/G_{n_1}\cong G_{n_2}$ and G_{n_2} is cyclic.
- (3) $|G_1|$ is a power of prime, and G is transitive on $Z_{n_1} \not\subset Z_{n_2}$, by the assumptions of this theorem.

Besides, since G is transitive on $Z_{n_1} \times Z_{n_2}$, G has only one orbit on $Z_{n_1} \times Z_{n_2}$. But the monotonicity and nontrivicity of f imply that the only orbit is not in Δ_f . Thus $\Delta_f^G = \{\phi\}$. This turns out $\chi(\Delta_f^G) = 0$. By Lemma 4, above results lead to the conclusion of current theorem. \square

Corollary 1 Let $f(x_1, x_2, \dots, x_n)$ be a nontrivial monotone Boolean function, $n = n_1 \cdot n_2$. If $f(x_1, x_2, \dots, x_n)$ is transitively invariant under the direct product $G_{n_1} \times G_{n_2}$ of permutation groups G_{n_1} and G_{n_2} , where G_{n_1} is a cyclic group of prime power order on $\{1, 2, \dots, n_1\}$, and G_{n_2} is a cyclic group on $\{1, 2, \dots, n_2\}$, then f is elusive.

Proof It is an immediate result of Theorem 1. \square

It is clearly that Corollary 1 partly answers the question of A. C-C. Yao.

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布尔函数的判定树复杂性及问题

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摘 要: 设 $f(x_1,x_2,\dots,x_n)$ 是一个布尔函数。如果计算 $f(x_1,x_2,\dots,x_n)$ 的每个判定树 算法在最坏情况下都要检查所有 n 个变量才能求得 f 的值,则称 f 是诡秘函数。 1988 年, A.C.C. Yao 提出一个问题:如果一个单调非平凡的布尔函数 $f(x_1,x_2,\dots,x_n)$ 在循环群 $C_m \times C_n$ 的直积的可迁作用下不变,则 f 是诡秘的吗?对这个问题的肯定回答支持著名的 Rivest-Vuillemin 猜想. 本文将部分地解答这一问题.