

# Extensions and Deformations of 3-Lie Algebras with Higher Derivations

Shuangjian GUO

*School of Mathematics and Statistics, Guizhou University of Finance and Economics,  
Guizhou 550025, P. R. China*

**Abstract** In this paper, we call a tuple consisting of 3-Lie algebra and a higher derivation on it a 3-LieHDer pair. We introduce a cohomology theory of 3-LieHDer pairs. Next, we interpret the second cohomology group as the space of all isomorphism classes of abelian extensions. Finally, we consider formal deformations of 3-LieHDer pairs that are governed by the cohomology with self-coefficient.

**Keywords** higher derivations; 3-LieHDer pairs; cohomology; extensions; formal deformations

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## 1. Introduction

Higher derivations were introduced by Hasse and Schmidt [1], therefore, they are also called Hasse-Schmidt derivations. Not all higher derivations arise from derivations in the above way. See [2, 3] for more results about higher derivations. Higher derivations are useful in the theory of automorphisms of complete local rings and Galois theory of fields.  $n$ -Lie algebras (also called Filippov algebras) have attracted attention from both mathematics and physics [4, 5]. As a special case of  $n$ -Lie algebras, 3-Lie algebras play important roles in the study of the Bagger-Lambert-Gustavsson theory of multiple M2-branes. Moreover, the metric 3-Lie algebras, or more generally, the 3-Lie algebras with invariant symmetric bilinear forms attract even more attentions in physics. 3-Lie algebras got a lot of attention [6–9].

Recently, the authors introduced the notion of LieDer pairs and studied extensions and deformations of LieDer pairs [10]. Later, the author studied associative algebras with higher derivations in [11]. Our aim in this paper is to consider 3-LieHDer pairs, which includes 3-Lie algebras and higher derivations. More precisely, we call a tuple consisting of 3-Lie algebra and a higher derivation on it a 3-LieHDer pair. We introduce a cohomology theory of 3-LieHDer pairs. Next, we study abelian extensions of a 3-LieHDer pair and relate them with the second cohomology group of the 3-LieHDer pair. Finally, we consider formal deformations of 3-LieHDer pairs that are governed by the cohomology with self-coefficient.

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E-mail address: shuangjianguo@126.com

The paper is organized as follows. In Section 2, we define representations of 3-LieHDer pairs and construct the semi-direct product. In Section 3, we introduce a cohomology theory of 3-LieHDer pairs. In Section 4, we interpret the second cohomology group as the space of all isomorphism classes of abelian extensions. In Section 5, we consider formal deformations of 3-LieHDer pairs that are governed by the cohomology with self-coefficient.

In this paper, we work over an algebraically closed field  $\mathbb{K}$  of characteristic 0 and all the vector spaces are over  $\mathbb{K}$  and finite-dimensional.

## 2. 3-LieHDer pairs and their representations

In this section, we define representations of 3-LieHDer pairs and construct the semi-direct product.

**Definition 2.1** Let  $(\mathfrak{g}, [\cdot, \cdot, \cdot])$  be a 3-Lie algebra. A higher derivation (of rank  $N$ ) on  $\mathfrak{g}$  is a tuple  $\mathbf{d} = (d_1, \dots, d_N)$  of linear maps on  $\mathfrak{g}$  satisfying the following identities

$$d_l([a, b, c]) = \sum_{i+j+k=l} [d_i(a), d_j(b), d_k(c)] \quad (2.1)$$

for  $l = 1, \dots, N$  and  $a, b, c \in \mathfrak{g}$ , with the convention that  $d_0 = \text{id}_{\mathfrak{g}}$ .

It follows from (2.1) that  $d_1$  is a derivation on  $\mathfrak{g}$ . In particular, if  $d$  is a derivation on  $\mathfrak{g}$ , then  $\mathbf{d} = (d)$  is a higher derivation of rank 1.

**Example 2.2** If  $d$  is a derivation on  $\mathfrak{g}$ , then  $\mathbf{d} = (d_1 = 0, \dots, d_i = d, \dots, d_N = 0)$  is a higher derivation of rank  $N$ .

**Example 2.3** Let  $d$  be a derivation on  $\mathfrak{g}$ . Then,  $\mathbf{d} = (d, \frac{d^2}{2!}, \dots, \frac{d^N}{N!})$  is a higher derivation of rank  $N$ .

**Example 2.4** Let  $\mathbf{d} = (d_1, \dots, d_N)$  be a higher derivation on  $\mathfrak{g}$ . For any  $1 \leq q \leq N$ , we define a new tuple  $\mathbf{d}' = (d'_1, \dots, d'_N)$  of linear maps by

$$d'_l = \begin{cases} 0, & \text{if } q \nmid l, \\ d_s, & \text{if } l = sq. \end{cases}$$

Then,  $\mathbf{d}' = (d'_1, \dots, d'_N)$  is a higher derivation of rank  $N$ .

Throughout the paper, by a higher derivation, we shall always mean a higher derivation of fixed rank  $N$ .

**Definition 2.5** Given 3-LieHDer pairs  $(\mathfrak{g}, \mathbf{d})$ ,  $(\mathfrak{g}', \mathbf{d}')$ , a homomorphism of 3-LieHDer pairs from  $(\mathfrak{g}, \mathbf{d})$  to  $(\mathfrak{g}', \mathbf{d}')$  is a 3-Lie algebra homomorphism  $\varphi : \mathfrak{g} \rightarrow \mathfrak{g}'$  such that  $\varphi \circ d_l = d'_l \circ \varphi$ ,  $l = 1, \dots, N$ .

Recall that a representation of a 3-Lie algebra  $\mathfrak{g}$  is a pair  $(V, \rho)$ , where  $V$  is a vector space,  $\rho : \wedge^2 \mathfrak{g} \rightarrow \mathfrak{gl}(V)$ ,  $a \wedge b \mapsto (v \mapsto \rho(a, b)v)$  is a homomorphism of 3-Lie algebras for all  $a, b \in \mathfrak{g}$  and  $v \in V$ .

**Definition 2.6** Let  $(\mathfrak{g}, \mathbf{d})$  be a 3-LieHDer pair.

(i) A representation over  $(\mathfrak{g}, \mathbf{d})$  is given by a pair  $(V, \rho)$  and linear maps  $\mathbf{d}^V = (d_1^V, \dots, d_N^V)$  satisfying

$$d_l^V(\rho(a, b)v) = \sum_{i+j+k=l} \rho(d_i(a), d_j(b))d_k^V(v), \quad l = 1, \dots, N$$

with convention that  $d_0 = \text{id}_{\mathfrak{g}}$  and  $d_0^V = \text{id}_V$ , for all  $x, y \in \mathfrak{g}, v \in V$ .

(ii) Let  $(U, \rho_U, \mathbf{d}^U)$  and  $(V, \rho_V, \mathbf{d}^V)$  be representations of  $(\mathfrak{g}, \mathbf{d})$ . If a linear map  $f : U \rightarrow V$  satisfies  $f \circ d_l^U = d_l^V \circ f, l = 1, \dots, N$  and

$$f \circ \rho_U(a, b) = \rho_V(a, b) \circ f, \quad \forall a, b \in \mathfrak{g},$$

then  $f$  is called a homomorphism of representations from  $(U, \rho_U, \mathbf{d}^U)$  to  $(V, \rho_V, \mathbf{d}^V)$ .

**Example 2.7** Let  $(\mathfrak{g}, \mathbf{d})$  be a 3-LieHDer pair. Then there is a natural representations

$$\rho : \wedge^2 \mathfrak{g} \rightarrow \mathfrak{gl}(\mathfrak{g}), \quad a \wedge b \mapsto (c \mapsto [a, b, c]).$$

This is called the adjoint representation over the 3-LieHDer pair  $(\mathfrak{g}, \mathbf{d})$ .

**Example 2.8** Let  $\mathfrak{g}$  be a 3-Lie algebra and  $(V, \rho)$  be a representation of it. Then the pair  $(V, \text{id}^V)$  is a representation of the 3-LieHDer pair  $(\mathfrak{g}, \text{id})$ .

It is easy to check the following proposition and we omit it.

**Proposition 2.9** Let  $(\mathfrak{g}, \mathbf{d})$  be a 3-LieHDer pair and  $(V, \mathbf{d}^V)$  be a representation of  $(\mathfrak{g}, \mathbf{d})$ . Define the multiplication  $[\cdot, \cdot, \cdot]$  on  $\mathfrak{g} \oplus V$  by

$$[a + u, b + v, c + w] = [a, b, c] + \rho(a, b)w + \rho(b, c)u + \rho(c, a)v, \quad \forall a, b, c \in \mathfrak{g}, u, v, w \in V$$

and linear maps  $d_l \oplus d_l^V : \mathfrak{g} \oplus V \rightarrow \mathfrak{g} \oplus V$  by

$$(d_l \oplus d_l^V)(x + u) = d_l(x) + d_l^V(u), \quad l = 1, \dots, N.$$

Then  $(\mathfrak{g} \oplus V, \mathbf{d} \oplus \mathbf{d}^V)$  is a 3-LieHDer pair.

### 3. Cohomology of 3-LieHDer pairs

In this section, we introduce the cohomology theory of 3-LieHDer pairs  $(\mathfrak{g}, \mathbf{d})$  with coefficients in a representation  $(V, \rho, \mathbf{d}^V)$ .

#### 3.1. Cohomology of 3-Lie algebras

Recall that the complex of 3-Lie algebra  $\mathfrak{g}$  with coefficients in representation  $V$  is the cochain complex

$$(C_{3\text{-Lie}}^*(\mathfrak{g}, V) = \oplus_{n=0}^{\infty} C_{3\text{-Lie}}^n(\mathfrak{g}, V), \partial_{3\text{-Lie}}^*),$$

where for  $n \geq 1$ ,  $C_{3\text{-Lie}}^n(\mathfrak{g}, V) = \text{Hom}(\underbrace{\wedge^2 \mathfrak{g} \otimes \dots \otimes \wedge^2 \mathfrak{g}}_{n-1} \wedge \mathfrak{g}, V)$  (in particular,  $C_{3\text{-Lie}}^0(\mathfrak{g}, V) = V$ )

and the coboundary operator  $\partial_{3\text{-Lie}}^n : C_{3\text{-Lie}}^n(\mathfrak{g}, V) \rightarrow C_{3\text{-Lie}}^{n+1}(\mathfrak{g}, V), n \geq 1$  is given by

$$\partial_{3\text{-Lie}}^n f(X_1, \dots, X_n, x_{n+1})$$

$$\begin{aligned}
&= (-1)^{n+1}\rho(y_n, x_{n+1})f(X_1, \dots, X_{n-1}, x_n) + \\
&\quad (-1)^{n+1}\rho(x_{n+1}, x_n)f(X_1, \dots, X_{n-1}, y_n) + \\
&\quad \sum_{j=1}^n (-1)^{j+1}\rho(x_j, y_j)f(X_1, \dots, \hat{X}_j, \dots, X_n, x_{n+1}) + \\
&\quad \sum_{j=1}^n (-1)^j f(X_1, \dots, \hat{X}_j, \dots, X_n, [x_j, y_j, x_{n+1}]) + \\
&\quad \sum_{1 \leq j < k \leq n} (-1)^j f(X_1, \dots, \hat{X}_j, \dots, X_{k-1}, [x_j, y_j, x_k] \wedge y_k + \\
&\quad x_k \wedge [x_j, y_j, y_k], X_{k+1}, \dots, X_n, x_{n+1})
\end{aligned}$$

for all  $f \in C_{3\text{-Lie}}^n(\mathfrak{g}, V)$ ,  $X_i = x_i \wedge y_i \in \wedge^2 \mathfrak{g}$ ,  $i = 1, 2, \dots, n$  and  $x_{n+1} \in \mathfrak{g}$ . The corresponding cohomology is denoted by  $H_{3\text{-Lie}}^*(\mathfrak{g}, V)$ . When  $V$  is the adjoint representation, we write

$$H_{3\text{-Lie}}^n(\mathfrak{g}) = H_{3\text{-Lie}}^n(\mathfrak{g}, V), \quad n \geq 1.$$

### 3.2. Cohomology of 3-LieHDer pairs

Now, we introduce a cohomology theory of the 3-LieHDer pairs  $(\mathfrak{g}, \mathbf{d})$  by the cohomology of 3-Lie algebras. With a slight abuse of notation, we still use  $d_l$ ,  $l = 1, \dots, N$  to denote the endomorphism on  $\wedge^2 \mathfrak{g}$  given by

$$d_l(X) = d_l(x) \wedge y + x \wedge d_l(y), \quad \forall X = x \wedge y \in \wedge^2 \mathfrak{g}.$$

Define the set of  $n$ -cochains by

$$C_{3\text{-LieHDer}}^n(\mathfrak{g}, V) := \begin{cases} C_{3\text{-Lie}}^n(\mathfrak{g}, V) \oplus C_{3\text{-Lie}}^{n-1}(\mathfrak{g}, V), & n \geq 2, \\ C_{3\text{-Lie}}^1(\mathfrak{g}, V) = \text{Hom}(\mathfrak{g}, V), & n = 1. \end{cases}$$

For  $n \geq 1$ , we define a linear map

$$\delta_l : C_{3\text{-Lie}}^n(\mathfrak{g}, V) \rightarrow C_{3\text{-Lie}}^n(\mathfrak{g}, V), \quad \text{for } l = 1, \dots, N$$

by

$$\delta_l f := \sum_{i_1 + \dots + i_n = l} f \circ (d_{i_1} \otimes \dots \otimes d_{i_n}) - d_l^V \circ f$$

for any  $f \in C_{3\text{-Lie}}^n(\mathfrak{g}, V)$ .

**Lemma 3.1** *The map  $\partial_{3\text{-Lie}}$  and  $\delta$  are commutative with each other, i.e.,  $\partial_{3\text{-Lie}} \circ \delta_l = \delta_l \circ \partial_{3\text{-Lie}}$ .*

**Proof** For any  $f \in C_{3\text{-Lie}}^n(\mathfrak{g}, V)$ ,  $l = 1, \dots, N$ , we have

$$\begin{aligned}
&\partial_{3\text{-Lie}} \circ \delta_l(f)(X_1, \dots, X_n, x_{n+1}) \\
&= (-1)^{n+1}\rho(y_n, x_{n+1})\delta_l(f)(X_1, \dots, X_{n-1}, x_n) + \\
&\quad (-1)^{n+1}\rho(x_{n+1}, x_n)\delta_l(f)(X_1, \dots, X_{n-1}, y_n) + \\
&\quad \sum_{j=1}^n (-1)^{j+1}\rho(x_j, y_j)\delta_l(f)(X_1, \dots, \hat{X}_j, \dots, X_n, x_{n+1}) +
\end{aligned}$$

$$\begin{aligned}
& \sum_{j=1}^n (-1)^j \delta_l(f)(X_1, \dots, \hat{X}_j, \dots, X_n, [x_j, y_j, x_{n+1}]) + \\
& \sum_{1 \leq j < k \leq n} (-1)^j \delta_l(f)(X_1, \dots, \hat{X}_j, \dots, X_{k-1}, [x_j, y_j, x_k] \wedge y_k + \\
& x_k \wedge [x_j, y_j, y_k], X_{k+1}, \dots, X_n, x_{n+1}) \\
= & (-1)^{n+1} \sum_{i_1 + \dots + i_n = l} \rho(y_n, x_{n+1}) f \circ (d_{i_1}(X_1), \dots, d_{i_{n-1}}(X_{n-1}), d_{i_n}(x_n)) - \\
& (-1)^{n+1} \rho(y_n, x_{n+1}) d_l^V \circ f(X_1, \dots, X_{n-1}, x_n) + \\
& (-1)^{n+1} \sum_{i_1 + \dots + i_n = l} \rho(x_{n+1}, x_n) f \circ (d_{i_1}(X_1), \dots, d_{i_{n-1}}(X_{n-1}), d_{i_n}(y_n)) - \\
& (-1)^{n+1} \rho(x_{n+1}, x_n) d_l^V \circ f(X_1, \dots, X_{n-1}, y_n) + \\
& \sum_{j=1}^n \sum_{i_1 + \dots + i_n = l} (-1)^{j+1} \rho(x_j, y_j) f \circ (d_{i_1}(X_1), \dots, \hat{X}_j, \dots, d_{i_{n-1}}(X_n), d_{i_n}(x_{n+1})) - \\
& \sum_{j=1}^n (-1)^{j+1} \rho(x_j, y_j) d_l^V \circ f(X_1, \dots, \hat{X}_j, \dots, X_n, x_{n+1}) + \\
& \sum_{j=1}^n \sum_{i_1 + \dots + i_n = l} (-1)^j f \circ (d_{i_1}(X_1), \dots, \hat{X}_j, \dots, d_{i_{n-1}}(X_n), d_{i_n}([x_j, y_j, x_{n+1}])) + \\
& \sum_{j=1}^n (-1)^j d_l^V \circ f(X_1, \dots, \hat{X}_j, \dots, X_n, x_n, [x_j, y_j, x_{n+1}]) + \\
& \sum_{1 \leq j < k \leq n} \sum_{i_1 + \dots + i_n = l} (-1)^j f \circ (d_{i_1}(X_1), \dots, \hat{X}_j, \dots, d_{i_{k-1}}(X_{k-1}), d_{i_k}([x_j, y_j, x_k]) \wedge y_k + \\
& x_k \wedge d_{i_k}([x_j, y_j, y_k]), d_{i_{k+1}}(X_{k+1}), \dots, d_{i_n}(X_n), d_{i_{n+1}}(x_{n+1})) - \\
& \sum_{1 \leq j < k \leq n} (-1)^j d_l^V \circ f(X_1, \dots, \hat{X}_j, \dots, X_{k-1}, [x_j, y_j, x_k] \wedge y_k + \\
& x_k \wedge [x_j, y_j, y_k], X_{k+1}, \dots, X_n, x_{n+1}) \\
= & \sum_{i_1 + \dots + i_n = l} (-1)^{n+1} \rho(y_n, x_{n+1}) f \circ (d_{i_1}(X_1), \dots, d_{i_{n-1}}(X_{n-1}), d_{i_n}(x_n)) - \\
& (-1)^{n+1} d_l^V \circ \rho(y_n, x_{n+1}) f(X_1, \dots, X_{n-1}, x_n) + \\
& \sum_{i_1 + \dots + i_n = l} (-1)^{n+1} \rho(x_{n+1}, x_n) f \circ (d_{i_1}(X_1), \dots, d_{i_{n-1}}(X_{n-1}), d_{i_n}(y_n)) - \\
& (-1)^{n+1} d_l^V \circ \rho(x_{n+1}, x_n) f(X_1, \dots, X_{n-1}, y_n) + \\
& \sum_{i_1 + \dots + i_n = l} \sum_{j=1}^n (-1)^{j+1} \rho(x_j, y_j) f \circ (d_{i_1}(X_1), \dots, \hat{X}_j, \dots, d_{i_{n-1}}(X_n), d_{i_n}(x_{n+1})) - \\
& \sum_{j=1}^n (-1)^{j+1} d_l^V \circ \rho(x_j, y_j) f(X_1, \dots, \hat{X}_j, \dots, X_n, x_{n+1}) + \\
& \sum_{i_1 + \dots + i_n = l} \sum_{j=1}^n (-1)^j f \circ (d_{i_1}(X_1), \dots, \hat{X}_j, \dots, d_{i_{n-1}}(X_n), d_{i_n}([x_j, y_j, x_{n+1}])) +
\end{aligned}$$

$$\begin{aligned}
& \sum_{j=1}^n (-1)^j d_l^V \circ f(X_1, \dots, \hat{X}_j, \dots, X_n, x_n, [x_j, y_j, x_{n+1}]) + \\
& \sum_{i_1 + \dots + i_n = l} \sum_{1 \leq j < k \leq n} (-1)^j f \circ (d_{i_1}(X_1), \dots, \hat{X}_j, \dots, d_{i_{k-1}}(X_{k-1}), d_{i_k}([x_j, y_j, x_k]) \wedge y_k + \\
& x_k \wedge d_{i_k}([x_j, y_j, y_k]), d_{i_{k+1}}(X_{k+1}), \dots, d_{i_n}(X_n), d_{i_{n+1}}(x_{n+1})) - \\
& \sum_{1 \leq j < k \leq n} (-1)^j d_l^V \circ f(X_1, \dots, \hat{X}_j, \dots, X_{k-1}, [x_j, y_j, x_k] \wedge y_k + \\
& x_k \wedge [x_j, y_j, y_k], X_{k+1}, \dots, X_n, x_{n+1}) \\
= & \delta_l((-1)^{n+1} \rho(y_n, x_{n+1}) f(X_1, \dots, X_{n-1}, x_n) + (-1)^{n+1} \rho(x_{n+1}, x_n) f(X_1, \dots, X_{n-1}, y_n) + \\
& \sum_{j=1}^n (-1)^{j+1} \rho(x_j, y_j) f(X_1, \dots, \hat{X}_j, \dots, X_n, x_{n+1}) + \\
& \sum_{j=1}^n (-1)^j f(X_1, \dots, \hat{X}_j, \dots, X_n, [x_j, y_j, x_{n+1}]) + \\
& \sum_{1 \leq j < k \leq n} (-1)^j f(X_1, \dots, \hat{X}_j, \dots, X_{k-1}, [x_j, y_j, x_k] \wedge y_k + x_k \wedge [x_j, y_j, y_k], X_{k+1}, \dots, X_n, x_{n+1})) \\
= & \delta_l \circ \partial_{3\text{-Lie}}(f)(X_1, \dots, X_n, x_{n+1}).
\end{aligned}$$

And the proof is completed.  $\square$

Define  $\partial_{3\text{-LieHDer}} : C_{3\text{-Lie}}^1(\mathfrak{g}, V) \rightarrow C_{3\text{-Lie}}^2(\mathfrak{g}, V)$  by

$$\partial_{3\text{-LieHDer}}(f) = (\partial_{3\text{-Lie}}(f), (-1)^1 \delta f), \quad \forall f \in C_{3\text{-Lie}}^1(\mathfrak{g}, V).$$

Then for  $n \geq 2$ , we define  $\partial_{3\text{-LieHDer}} : C_{3\text{-Lie}}^n(\mathfrak{g}, V) \rightarrow C_{3\text{-Lie}}^{n+1}(\mathfrak{g}, V)$  by

$$\partial_{3\text{-LieHDer}}(f_n, g_{n-1}) = (\partial_{3\text{-Lie}}(f_n), \partial_{3\text{-Lie}}(g_{n-1}) + (-1)^n \delta_l f_n)$$

for any  $f_n \in C_{3\text{-Lie}}^n(\mathfrak{g}, V), g_{n-1} \in C_{3\text{-Lie}}^{n-1}(\mathfrak{g}, V)$ .

**Theorem 3.2** *The pair  $(C_{3\text{-LieHDer}}^*(\mathfrak{g}, V), \partial_{3\text{-LieHDer}})$  is a cochain complex. So*

$$\partial_{3\text{-LieHDer}}^2 = 0.$$

**Proof** For any  $v \in C_{3\text{-Lie}}^1(\mathfrak{g}, V), l = 1, \dots, N$ , we have

$$\partial_{3\text{-LieHDer}}^2 v = \partial_{3\text{-LieHDer}}(\partial_{3\text{-Lie}} v, \delta_l v) = (\partial_{3\text{-Lie}}^2 v, \partial_{3\text{-Lie}} \delta_l v - \delta_l \partial_{3\text{-Lie}} v) = 0.$$

Given any  $f \in C_{3\text{-Lie}}^n(\mathfrak{g}, V), g \in C_{3\text{-Lie}}^{n-1}(\mathfrak{g}, V)$  with  $n \geq 2, l = 1, \dots, N$ , we have

$$\begin{aligned}
\partial_{3\text{-LieHDer}}^2(f, g) &= \partial_{3\text{-LieHDer}}(\partial_{3\text{-Lie}} f, \partial_{3\text{-Lie}} g + (-1)^n \delta_l f) \\
&= (\partial_{3\text{-Lie}}^2 f, \partial_{3\text{-Lie}}(\partial_{3\text{-Lie}} g + (-1)^n \delta_l f) + (-1)^{n+1} \delta_l \partial_{3\text{-Lie}} f) \\
&= 0.
\end{aligned}$$

Therefore,  $(C_{3\text{-LieHDer}}^*(\mathfrak{g}, V), \partial_{3\text{-LieHDer}})$  is a cochain complex.  $\square$

**Definition 3.3** *The cohomology of the cochain complex  $(C_{3\text{-LieHDer}}^*(\mathfrak{g}, V), \partial_{3\text{-LieHDer}})$ . The corresponding cohomology groups are denoted by  $H_{3\text{-LieHDer}}^*(\mathfrak{g}, V)$ .*

#### 4. Abelian extensions of 3-LieHDer pairs

In this section, we interpret the second cohomology group as the space of all isomorphism classes of abelian extensions of 3-LieHDer pairs.

**Definition 4.1** *An abelian extension of the 3-LieHDer pairs  $(\mathfrak{g}, \mathbf{d})$  by the pair  $(V, \mathbf{d}^V)$  is another 3-LieHDer pair  $(\hat{\mathfrak{g}}, \hat{\mathbf{d}})$  with a short exact sequence*

$$\begin{array}{ccccccc} 0 & \longrightarrow & V & \xrightarrow{i} & \hat{\mathfrak{g}} & \xrightarrow{p} & \mathfrak{g} \longrightarrow 0 \\ & & \downarrow v & & \downarrow \hat{d} & & \downarrow d \\ 0 & \longrightarrow & V & \xrightarrow{i} & \hat{\mathfrak{g}} & \xrightarrow{p} & \mathfrak{g} \longrightarrow 0 \end{array}$$

Diagram 1 Exact sequence diagram

of 3-LieHDer pairs.

**Definition 4.2** *Let  $(\hat{\mathfrak{g}}, \hat{\mathbf{d}})$  and  $(\hat{\mathfrak{g}}', \hat{\mathbf{d}}')$  be two abelian extensions of the 3-LieHDer pairs  $(\mathfrak{g}, \mathbf{d}_{\mathfrak{g}})$  by the pair  $(V, \mathbf{d}^V)$ . These two abelian extensions are said to be isomorphic if there exists an isomorphism  $\zeta : (\hat{\mathfrak{g}}, \hat{\mathbf{d}}) \rightarrow (\hat{\mathfrak{g}}', \hat{\mathbf{d}}')$  of 3-LieHDer pairs that make the following diagram commutative:*

$$\begin{array}{ccccccc} 0 & \longrightarrow & (V, \mathbf{d}^V) & \xrightarrow{i} & (\hat{\mathfrak{g}}, \hat{\mathbf{d}}) & \xrightarrow{p} & (\mathfrak{g}, \mathbf{d}) \longrightarrow 0 \\ & & \parallel & & \downarrow \zeta & & \parallel \\ 0 & \longrightarrow & (V, \mathbf{d}^V) & \xrightarrow{i} & (\hat{\mathfrak{g}}', \hat{\mathbf{d}}') & \xrightarrow{p} & (\mathfrak{g}, \mathbf{d}) \longrightarrow 0. \end{array}$$

Diagram 2 The isomorphism diagram

A section of an abelian extension  $(\hat{\mathfrak{g}}, \hat{\mathbf{d}})$  of  $(\mathfrak{g}, \mathbf{d})$  by  $(V, \mathbf{d}^V)$  is a linear map  $\sigma : \mathfrak{g} \rightarrow \hat{\mathfrak{g}}$  such that  $p \circ \sigma = \text{id}_{\mathfrak{g}}$ .

Now for an abelian extension  $(\hat{\mathfrak{g}}, \hat{\mathbf{d}})$  of  $(\mathfrak{g}, \mathbf{d})$  by  $(V, \mathbf{d}^V)$  with a section  $\sigma : \mathfrak{g} \rightarrow \hat{\mathfrak{g}}$ , we define a linear map  $\rho : \wedge^2 \mathfrak{g} \rightarrow \mathfrak{gl}(V)$  by

$$\rho(x, y)v := \rho(\sigma(x), \sigma(y))v, \quad \forall x, y \in \mathfrak{g}, v \in V.$$

**Proposition 4.3** *With the above notations,  $(V, \mathbf{d}^V)$  is a representation over the 3-LieHDer pair  $(\mathfrak{g}, \mathbf{d})$ .*

**Proof** It is routine to check that  $\rho$  is a representation of the 3-Lie algebra  $\mathfrak{g}$  on  $V$ . Moreover,  $\hat{d}_l(\sigma(x)) - \sigma(d_l(x)) \in V$  means that

$$\rho(\hat{d}_l(\sigma(x)), \hat{d}_l(\sigma(y)))v = \rho(\sigma(d_l(x)), \sigma(d_l(y)))v \text{ for } l = 1, \dots, N.$$

Thus we have

$$\begin{aligned} d_l^V(\rho(x, y)v) &= d_l^V(\rho(\sigma(x), \sigma(y))v) \\ &= \sum_{i+j+k=l} \rho(\hat{d}_i(\sigma(x)), \hat{d}_j(\sigma(y)))d_k^V(v) \end{aligned}$$

$$\begin{aligned}
&= \sum_{i+j+k=l} \rho(\sigma(d_i(x)), \sigma(d_j(y))) d_k^V(v) \\
&= \sum_{i+j+k=l} \rho(d_i(x), d_j(y)) d_k^V(v).
\end{aligned}$$

Hence,  $(V, \mathbf{d}^V)$  is a representation over  $(\mathfrak{g}, \mathbf{d})$ .  $\square$

We further define linear maps  $\psi : \wedge^3 \mathfrak{g} \rightarrow V$  and  $\chi_l : \mathfrak{g} \rightarrow V$  for  $l = 1, \dots, N$ , respectively by

$$\begin{aligned}
\psi(x, y, z) &= [\sigma(x), \sigma(y), \sigma(z)] - \sigma([x, y, z]), \quad \forall x, y, z \in \mathfrak{g}, \\
\chi_l(x) &= \hat{d}_l(\sigma(x)) - \sigma(d_l(x)), \quad \forall x \in \mathfrak{g}.
\end{aligned}$$

We set  $\hat{\mathfrak{g}}$  to  $\mathfrak{g} \oplus V$ . Then we define a trilinear multiplication  $[\cdot, \cdot, \cdot]_\psi : \wedge^3 \hat{\mathfrak{g}} \rightarrow \hat{\mathfrak{g}}$  and a linear map  $\mathbf{d}^X : \hat{\mathfrak{g}} \rightarrow \hat{\mathfrak{g}}$  by

$$[a + u, b + v, c + w]_\psi = [a, b, c] + \rho(a, b)v + \rho(b, c)u + \rho(c, a)v + \psi(a, b, c), \quad (4.1)$$

$$d_l^X(a + v) = d_l(a) + \chi_l(x) + d_l^V(v), \quad l = 1, \dots, N \quad (4.2)$$

for any  $a, b, c \in \mathfrak{g}$ ,  $u, v, w \in V$ .

**Proposition 4.4** *The triple  $(\mathfrak{g} \oplus V, [\cdot, \cdot, \cdot]_\psi, \mathbf{d}^X)$  equipped with the above product and the tuple  $\mathbf{d}^X = (d_1^X, \dots, d_N^X)$  of linear maps forms a 3-LieHDer pair of rank  $N$  if and only if  $(\psi, \chi_1, \dots, \chi_N)$  is a 2-cocycle of the 3-LieHDer pair  $(\mathfrak{g}, \mathbf{d})$  with the coefficient in  $(V, \mathbf{d}^V)$ .*

**Proof** Suppose that  $(\mathfrak{g} \oplus V, [\cdot, \cdot, \cdot]_\psi, \mathbf{d}^X)$  is a 3-LieHDer pair for any  $a, b, c \in \mathfrak{g}$ , one can easily observe that  $[\cdot, \cdot, \cdot]_\psi$  satisfies

$$\psi(a, [b, c]) + \psi(a, \psi(b, c)) + \psi(b, [c, a]) + \psi(b, \psi(c, a)) + \psi(c, [a, b]) + \psi(c, \psi(a, b)) = 0. \quad (4.3)$$

Since  $\mathbf{d}^X$  satisfies (2.1) for  $l = 1, \dots, N$ , we deduce that

$$\chi_l([a, b, c]) + d_l^V(\psi(a, b, c)) = \sum_{i+j+k=l} \psi(d_i(a), d_j(b), d_k(c)). \quad (4.4)$$

Hence,  $(\psi, \chi_1, \dots, \chi_N)$  is a 2-cocycle.

Conversely, if  $(\psi, \chi_1, \dots, \chi_N)$  satisfies equalities (4.1) and (4.2). Since  $\partial_{3\text{-Lie}}(\psi) = 0$ , it follows that  $[\cdot, \cdot, \cdot]_\psi$  defines a 3-Lie algebra structure on  $\hat{\mathfrak{g}}$ . On the other hand,

$$\partial_{3\text{-Lie}}(\chi_l) + \delta_l(\psi) = 0$$

implies that  $\mathbf{d}^X$  is a higher derivation. And the proof is completed.  $\square$

Now we give the important theorems in this section.

**Theorem 4.5** *Let  $(\mathfrak{g}, \mathbf{d})$  be a 3-LieHDer pair and  $(V, \mathbf{d}^V)$  be a trivial 3-LieHDer pair. Then, the isomorphism classes of abelian extensions of  $\mathfrak{g}$  by  $V$  are classified by the second cohomology group.*

**Proof** Let  $(\hat{\mathfrak{g}}, \hat{\mathbf{d}})$  be an abelian extension of  $(\mathfrak{g}, \mathbf{d})$  by  $(V, \mathbf{d}^V)$ . If  $\sigma_1 : \mathfrak{g} \rightarrow \hat{\mathfrak{g}}$  is a section of the map  $p$  and  $(\psi^1, \chi_1^1, \dots, \chi_N^1)$  is a corresponding 2-cocycle. Let  $(\psi^2, \chi_1^2, \dots, \chi_N^2)$  be a 2-cocycles



and the section  $\sigma_1$ . We define  $\omega : \mathfrak{g} \rightarrow V$  by

$$\omega(x) = \sigma_1(x) - \sigma_2(x).$$

Then

$$\begin{aligned} \psi^1(x, y, z) &= [\sigma_1(x), \sigma_1(y), \sigma_1(z)] - \sigma_1([x, y, z]) \\ &= [\sigma_2(x) + \omega(x), \sigma_2(y) + \omega(y), \sigma_2(z) + \omega(z)] - (\sigma_2([x, y, z]) + \omega([x, y, z])) \\ &= \psi^2(x, y, z) + \partial\omega(x, y, z) \end{aligned}$$

and

$$\begin{aligned} \chi_l^1(x) &= \hat{d}_l(\sigma_1(x)) - \sigma_1(d_l(x)) \\ &= \hat{d}_l(\sigma_2(x) + \omega(x)) - (\sigma_2(d_l(x)) + \omega(d_l(x))) \\ &= (\hat{d}_l(\sigma_2(x)) - \sigma_2(d_l(x))) + \hat{d}_l(\omega(x)) - \omega(d_l(x)) \\ &= \chi_l^2(x) + d_l^V(\omega(x)) - \omega(d_l(x)) \\ &= \chi_l^2(x) - \delta\omega(x). \end{aligned}$$

That is,

$$(\psi^1, \chi_1^1, \dots, \chi_N^1) = (\psi^2, \chi_1^2, \dots, \chi_N^2) + \partial_{\mathfrak{3}\text{-LieHDer}}(\omega).$$

Thus  $(\psi^1, \chi_1^1, \dots, \chi_N^1)$  and  $(\psi^2, \chi_1^2, \dots, \chi_N^2)$  are in the same cohomological class in  $H_{\mathfrak{3}\text{-LieHDer}}^2(\mathfrak{g}, V)$ .

Let  $(\hat{\mathfrak{g}}, \hat{\mathbf{d}})$  and  $(\hat{\mathfrak{g}}', \hat{\mathbf{d}}')$  be two isomorphic abelian extensions,  $\sigma_1$  be a section of  $(\hat{\mathfrak{g}}, \hat{\mathbf{d}})$ . As  $\pi_2 \circ \xi = \pi_1$ , we have

$$\pi_2 \circ (\xi \circ \sigma_1) = \pi_1 \circ \sigma_1 = \text{id}_{\mathfrak{g}}.$$

Therefore,  $\zeta \circ \sigma_1$  is a section of  $(\hat{\mathfrak{g}}', \hat{\mathbf{d}}')$ . Denote  $\sigma_2 := \xi \circ \sigma_1$ . Since  $\xi : (\hat{\mathfrak{g}}, \hat{\mathbf{d}}) \rightarrow (\hat{\mathfrak{g}}', \hat{\mathbf{d}}')$  is a homomorphism of 3-LieHDer pairs such that  $\xi|_V = \text{id}_V$  for  $l = 1, \dots, N$ , we have

$$\begin{aligned} \psi^2(x, y, z) &= [\sigma_2(x), \sigma_2(y), \sigma_2(z)] - \sigma_2([x, y, z]) \\ &= [\xi(\sigma_1(x)), \xi(\sigma_1(y)), \xi(\sigma_1(z))] - \xi(\sigma_1([x, y, z])) \\ &= \xi([\sigma_1(x), \sigma_1(y), \sigma_1(z)] - \sigma_1([x, y, z])) = \xi(\psi^1(x, y, z)) \\ &= \psi^1(x, y, z) \end{aligned}$$

and

$$\begin{aligned} \chi_l^2(x) &= \hat{d}'_l(\sigma_2(x)) - \sigma_2(\hat{d}_l(x)) = \hat{d}'_l(\zeta(\sigma_1(x))) - \zeta(\sigma_1(\hat{d}_l(x))) \\ &= \xi(\hat{d}_l(\sigma_1(x)) - \sigma_1(\hat{d}_l(x))) = \xi(\chi_l^1(x)) \\ &= \chi_l^1(x). \end{aligned}$$

Consequently, all isomorphic abelian extensions give rise to the same element in  $H_{\mathfrak{3}\text{-LieHDer}}^2(\mathfrak{g}, V)$ .

Conversely, let  $(\psi^2, \chi_1^2, \dots, \chi_N^2)$  be another 2-cocycle cohomologous to  $(\psi^1, \chi_1^1, \dots, \chi_N^1)$ . In other words, they represent the same cohomological class in  $H_{\mathfrak{3}\text{-LieHDer}}^2(\mathfrak{g}, V)$ , then there exists a linear map  $\omega : \mathfrak{g} \rightarrow V$  such that

$$(\psi^1, \chi_1^1, \dots, \chi_N^1) = (\psi^2, \chi_1^2, \dots, \chi_N^2) + \partial_{\mathfrak{3}\text{-LieHDer}}(\omega).$$

Define

$$\xi : \mathfrak{g} \oplus V \rightarrow \mathfrak{g} \oplus V \text{ by } \xi(x, v) := x + \omega(x) + v.$$

Then  $\xi$  is an isomorphism of these two abelian extensions.  $\square$

## 5. Formal deformations of 3-LieHDer pairs

Let  $(\mathfrak{g}, \mathbf{d})$  be a 3-LieHDer pair. Denote by  $\mu_{\mathfrak{g}}$  the multiplication of  $\mathfrak{g}$ .

**Definition 5.1** A 1-parameter formal deformation of a 3-LieHDer pair  $(\mathfrak{g}, \mathbf{d})$  consists of  $N + 1$  formal power series  $(\mu_t; d_{1,t}, \dots, d_{N,t})$  of the form.

$$\begin{aligned} \mu_t &= \sum_{i=0}^{\infty} \mu_i t^i, \\ d_{1,t} &= \sum_{i=0}^{\infty} t^i d_{1,i} \quad d_{1,0} = d_1, \\ &\vdots \\ d_{N,t} &= \sum_{i=0}^{\infty} t^i d_{N,i} \quad d_{N,0} = d_N, \end{aligned}$$

such that  $(\mathfrak{g}[[t]], \mu_t)$  is a 3-Lie algebra over  $\mathbb{K}[[t]]$  and the tuple  $d_t = (d_{1,t}, \dots, d_{N,t})$  is a higher derivation of rank  $N$ .

It follows that  $(\mu_t; d_{1,t}, \dots, d_{N,t})$  is a formal one-parameter deformation of the 3-LieHDer pair  $(\mathfrak{g}, \mathbf{d})$  if and only if the followings are hold:

$$\begin{aligned} \mu_t(a, b, \mu_t(c, d, e)) &= \mu_t(\mu_t(a, b, c), d, e) + \mu_t(c, \mu_t(a, b, d), e) + \mu_t(c, d, \mu_t(a, b, e)), \\ d_{l,t}(\mu_t(a, b, c)) &= \sum_{i+j+k=l} \mu_t(d_{i,t}(a), d_{j,t}(b), d_{k,t}(c)) \end{aligned}$$

for  $l = 1, \dots, N$ . The above identities are equivalent to

$$\begin{aligned} \sum_{i+j=n} \mu_i(a, b, \mu_j(c, d, e)) &= \sum_{i+j=n} \mu_i(\mu_j(a, b, c), d, e) + \mu_i(c, \mu_j(a, b, d), e) + \mu_i(c, d, \mu_j(a, b, e)), \\ \sum_{i+j=n} d_{l,i} \mu_j(a, b, c) &= \sum_{i+j+k=l} \sum_{p+q+r+s=n} (\mu_p(d_{i,q}(a), d_{j,r}(b), d_{k,s}(c))) \end{aligned}$$

for  $n \geq 0$ . The equations are hold for  $n = 0$  as  $d_{l,0} = d_l$ . However, for  $n = 1$ , we get

$$\begin{aligned} &\mu_1(a, b, [c, d, e]) + [a, b, \mu_1(c, d, e)] \\ &= \mu_1([a, b, c], d, e) + [\mu_1(a, b, c), d, e] + [c, \mu_1(a, b, d), e] + \\ &\quad \mu_1(c, [a, b, d], e) + [c, d, \mu_1(a, b, e)] + \mu_1(c, d, [a, b, e]) \end{aligned} \tag{5.1}$$

and

$$\begin{aligned} d_l \mu_1(a, b, c) + d_{l,1}[a, b, c] &= \sum_{i+j+k=l} \{(\mu_1(d_i(a), d_j(b), d_k(c))) + \\ &\quad [d_{i,1}(a), d_j(b), d_k(c)] + [d_i(a), d_{j,1}(b), d_k(c)] + [d_i(a), d_j(b), d_{k,1}(c)]\} \end{aligned} \tag{5.2}$$

for  $l = 1, \dots, N$ . For  $n = 1$ , (5.1) is equivalent to  $\partial_{3\text{-Lie}}\mu_1 = 0$ , and (5.2) is equivalent to

$$\partial_{3\text{-Lie}}d_{l,1} + \delta_l\mu_1 = 0.$$

Therefore, we have

$$\partial_{3\text{-LieHDer}}(\mu_1; d_{1,1}, \dots, d_{N,1}) = 0.$$

As a consequence of the above discussions, we obtain the following.

**Proposition 5.2** *Let  $(\mathfrak{g}, \mathbf{d})$  be a 3-LieHDer pair. Suppose  $(\mu_t; d_{1,t}, \dots, d_{N,t})$  is a formal one parameter deformation of  $(\mathfrak{g}, \mathbf{d})$ . Then the infinitesimal is a 2-cocycle in the cohomology complex of  $(\mathfrak{g}, \mathbf{d})$  with coefficients in itself. Moreover, the corresponding cohomology class depends only on the equivalence class of the deformation.*

The 2-cocycle is called the infinitesimal of the formal one-parameter deformation  $(\mu_t; d_{1,t}, \dots, d_{N,t})$ .

**Definition 5.3** *Let  $(\mu_t; d_{1,t}, \dots, d_{N,t})$  and  $(\mu'_t; d'_{1,t}, \dots, d'_{N,t})$  be two deformations of a 3-LieHDer pair  $(\mathfrak{g}, \mathbf{d})$ . They are said to be equivalent if there exists a formal isomorphism*

$$\Phi_t = \sum_{i \geq 0} \Phi_i t^i : \mathfrak{g}[[t]] \rightarrow \mathfrak{g}[[t]],$$

where  $\Phi_i : \mathfrak{g} \rightarrow \mathfrak{g}$  are linear maps with  $\Phi_0 = \text{id}_{\mathfrak{g}}$ , such that

$$\begin{aligned} \Phi_t \circ \mu_t &= \mu'_t \circ (\Phi_t \times \Phi_t \times \Phi_t), \\ \Phi_t \circ d_{l,t} &= d'_{l,t} \circ \Phi_t, \text{ for } l = 1, \dots, N. \end{aligned}$$

They are equivalent to the following equations: for  $n \geq 0$ ,

$$\begin{aligned} \sum_{i+j=n} \Phi_i \circ \mu_j &= \sum_{p+q+r+s=n} \mu'_p \circ (\Phi_q \times \Phi_r \times \Phi_s), \\ \sum_{i+j=n} \Phi_i \circ d_{l,j} &= \sum_{p+q=n} d'_{l,p} \circ \Phi_q \text{ for } l = 1, \dots, N. \end{aligned}$$

The above identities hold for  $n = 0$ . For  $n = 1$ , we have

$$\begin{aligned} \mu_1 + \Phi_1 \circ \mu &= \mu'_1 + \mu \circ (\Phi_1 \times \text{id} \times \text{id}) + \mu \circ (\text{id} \times \Phi_1 \times \text{id}) + \mu \circ (\text{id} \times \text{id} \times \Phi_1), \\ d_l \circ \Phi_1 + d'_{l,1} &= d_{l,1} + \Phi_1 \circ d_l \text{ for } l = 1, \dots, N. \end{aligned}$$

Thus, we have

$$(\mu_1; d_{1,1}, \dots, d_{N,1}) - (\mu'_1; d'_{1,1}, \dots, d'_{N,1}) = \partial_{3\text{-LieHDer}}(\Phi_1).$$

**Proposition 5.4** *The corresponding cohomology class depends only on the equivalence class of the deformation.*

**Definition 5.5** *If the deformation  $(\mu_t; d_{1,t}, \dots, d_{N,t})$  is equivalent to the undeformed deformation  $(\mu'_t = \mu; d'_{1,t} = d_1, \dots, d'_{N,t} = d_N)$ , then it is called trivial.*

**Theorem 5.6** *If  $H_{3\text{-LieHDer}}^2(\mathfrak{g}, \mathfrak{g}) = 0$ , then every formal deformation of the 3-LieHDer pair  $(\mathfrak{g}, \mathbf{d})$  is trivial.*

**Proof** Suppose  $(\mu_t; d_{1,t}, \dots, d_{N,t})$  is a deformation of the 3-LieHDer pair  $(\mathfrak{g}, \mathbf{d})$ , we obtain that the linear term  $(\mu_1; d_{1,1}, \dots, d_{N,1})$  is a 2-cocycle according to Proposition 5.2. By

$$H_{3\text{-LieHDer}}^2(\mathfrak{g}, \mathfrak{g}) = 0,$$

there exists a 1-cochain  $\Phi_1 \in C_{3\text{-Lie}}^1(\mathfrak{g}, \mathfrak{g})$  such that

$$(\mu_1; d_{1,1}, \dots, d_{N,1}) = \partial_{3\text{-LieHDer}}(\phi_1). \quad (5.3)$$

We set  $\Phi_t = \text{id}_{\mathfrak{g}} + \Phi_1 t$  and define

$$\mu'_t = \Phi_t^{-1} \circ \mu_t \circ \Phi_t \times \Phi_t \times \Phi_t, \quad d'_{l,t} = \Phi_t^{-1} \circ d_{l,t} \circ \Phi_t, \quad l = 1, \dots, N.$$

By definition,  $(\mu'_t; d'_{1,t}, \dots, d'_{N,t})$  is equivalent to  $(\mu_t; d_{1,t}, \dots, d_{N,t})$ . Moreover, it follows from (5.3), we have

$$\mu'_t = \mu + \mu'_2 t^2 + \dots, \quad d'_{l,t} = d_k + d'_{l,2} t^2 + \dots.$$

In other words, the linear terms vanish. By repeating this argument, we conclude the result.  $\square$

## 6. Conclusions

In this paper, we study 3-Lie algebras equipped with higher derivations.

Like higher derivations are generalization of the usual derivative, Rota-Baxter operators on 3-Lie algebras are generalization of the integral operator. Let  $\mathfrak{g}$  be a 3-Lie algebra. A linear map  $R : \mathfrak{g} \rightarrow \mathfrak{g}$  is called a Rota-Baxter operator (of weight 0) on  $\mathfrak{g}$  if  $R$  satisfies

$$[R(x), R(y), R(z)] = R([R(x), R(y), z] + [x, R(y), R(z)] + [R(x), y, R(z)]), \quad \forall x, y, z \in \mathfrak{g}.$$

See [12, 13] for more details about Rota-Baxter operators on 3-Lie algebras. By generalizing higher integral operators, one may define the notion of higher Rota-Baxter operator of rank  $N$ . More precisely, a higher Rota-Baxter operator of rank  $N$  consists of a tuple  $R = (R_1, \dots, R_N)$  of linear maps satisfying the following identities

$$[R_l(x), R_l(y), R_l(z)] = R_l\left(\sum_{i+j+k=l} [R_i(x), R_j(y), R_k(z)]\right) \text{ for } l = 1, \dots, N.$$

With the convention that  $R_0 = \text{id}_{\mathfrak{g}}$ . If  $R$  is a Rota-Baxter operator on  $\mathfrak{g}$ , then it is easy to see that

$$R = \left(R, \frac{R^2}{2!}, \dots, \frac{R^N}{N!}\right)$$

is a higher Rota-Baxter operator of rank  $N$ . In future, we come with more structural properties of higher Rota-Baxter operators.

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